

1MHz - 6000MHz

Device Features

- 6-bit Serial & Parallel Interface
- 31.5 dB Control Range 0.5 dB step
- Glitch-safe attenuation state transitions
- 2.7 V to 5.5 V supply
- 1.8 V or 3.3 V control logic
- Excellent Attenuation Accuracy
 Any bit Attenuation Error < ±0.5 dB up to 6GHz
- Low Insertion Loss
 - 0.7 dB @ 1GHz
 - 0.9 dB @ 2GHz
 - 1.1 dB @ 3GHz
 - 1.3 dB @ 4GHz
 - 1.8 dB @ 5GHz
- Ultra linearity IIP3 > +63 dBm @ 3.5GHz, ATT=0dB
- Input 0.1dB Compression (P0.1dB) 30dBm @ 3.5GHz, ATT=0dB
- Programming modes
 - Direct parallel
 - Latched parallel
 - Serial
- Stable Integral Non-Linearity over temperature
- Low Current Consumption 200 μA typical
- -40 °C to +105 °C operating temperature
- ESD rating : Class1C (1KV HBM)
- Lead-free/RoHS2-compliant 20-lead 4mm x 4mm x 0.9mm QFN SMT package



Product Description

The BDA4620 is a broadband, Highly accurate 50Ω digital step attenuator model which provides adjustable attenuation from 0 to 31.5 dB in 0.5 dB steps. The control is a 6-bit serial interface and latched parallel interface.

BDA4620 supports a broad operating frequency range from 1MHz to 6.0 GHz. BDA4620 is offering the High linearity, low power consumption, low insertion loss, high attenuation accuracy and low insertion loss less than 2.0dB typical at all frequency band.

The device features a safe state transitions with no negative/positive Glitch technology optimized for excellent step accuracy.

The RF input and output are internally matched to $50~\Omega$ and do not require any external matching components. The design is bidirectional; therefore, the RF input and output are interchangeable. BDA4620 also features an external negative supply option.

This DSA does not require blocking capacitors. If DC is presented at the RF port, add a blocking capacitor.

It is packaged in a RoHS2-compliant with QFN surface mount package.



20-lead 4mm x 4 mm x 0.9mm QFN

Figure 1. Package Type

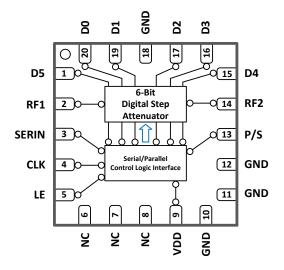


Figure 2. Functional Block Diagram

Application

- 5G/4G+/4G/3G Cellular Base station/Repeater Infrastructure
- Digital Pre-Distortion
- Distributed Antenna Systems, DAS
- Remote Radio Heads
- NFC Infrastructure
- Test Equipment and sensors
- Military Wireless system
- Cable Infrastructure
- General purpose Wireless

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Table 1. Electrical Specifications¹

	Parameter	Condition	Frequency	Min	Тур	Max	Unit	
Operati	ing Frequency Range			1		6000	MHz	
At	tenuation range	0.5dB step			0 - 31.5		dB	
-		ATT = 0dB	1MHz - 1GHz		0.6	0.7	dB	
		ATT = 0dB	> 1 - 2.2GHz		0.8	1.0	dB	
lı	nsertion Loss ²	ATT = 0dB	> 2.2 - 3GHz		1.0	1.1	dB	
		ATT = 0dB	> 3 - 4GHz		1.2	1.3	dB	
		ATT = 0dB	> 4 - 6GHz		1.9	2.7	dB	
			1MHz - 1GHz			\pm (0.10 + 1.0% of attenuation state)	dB	
			> 1 - 2.2GHz			\pm (0.15 + 1.5% of attenuation state)	dB	
At	tenuation Error	0-31.5dB	> 2.2 - 3GHz			\pm (0.15 + 2.5% of attenuation state)	dB	
			> 3 - 4GHz			\pm (0.25 +3.5% of attenuation state)	dB	
			> 4 - 6GHz			\pm (0.25 +5.0% of attenuation state)	dB	
	out Poturn Loss	ATT = 0dB	1 - 4GHz		20		dB	
inp	out Return Loss	ATT = OdB	> 4 - 6GHz		10		ав	
04	tput Return Loss	ATT = 0dB	1 - 4GHz		21		dB	
Out	iput Keturn Loss	ATT = OUB	> 4 - 6GHz 11		11		ub	
			1GHz		7			
			2GHz		15			
Dala	tivo Dhaca Curar	All states	3GHz 24		24		dograa	
Keia	ative Phase Error	All states	4GHz		33		degree	
			5GHz		41			
			6GHz		50			
	Input 0.1dB Compression point	ATT = 0dB	3.5GHz		30		dBm	
		Pin = +18dBm/tone, $\triangle f$ = 10kHz	2.5GHz		52			
		ATT = 0.0dB	3.5GHz		63		dBm	
		RF Input = RF1 Port	4.5GHz		56			
		Pin = +18dBm/tone, $\triangle f = 10kHz$	2.5GHz		58			
Input		ATT = 31.5dB	3.5GHz		54		dBm	
Linearity		RF Input = RF1 Port	4.5GHz		53			
	Input IP3	Pin = +18dBm/tone, $\triangle f = 10kHz$	2.5GHz		57			
		ATT = 0.0dB	3.5GHz		60		dBm	
		RF Input = RF2 Port	4.5GHz		55		u5	
		,						
		Pin= +18dBm/tone, $\triangle f$ = 10kHz	2.5GHz		46		,_	
		ATT = 31.5dB	3.5GHz		56		dBm	
		RF Input = RF2 Port	4.5GHz		55			
	sing / Falling Time	10%/90% RF	2GHz		110		ns	
S	Switching time	50% CTRL to 90% or 10% RF	2GHz		210		ns	
	Settling time	50% CTRL to Max or Min Attenuation	2GHz		400		ns	
		to settle within 0.05 dB of final value	+		0.3			
	on transient(envelope) ³	Positive Glitch, Any ATT step	+		0.3		dB	
	num Spurious level on any RF port	Measured at RF ports			< -145		dBm	

^{1.} Device performance is measured on a BeRex Evaluation board Kit at 25°C, 50 Ω system, VDD=+3.3V 2. The Evaluation board Kit insertion loss (PCB & RF Connector) is de-embedded.

^{3.} Attenuation Transient is glitch level due to attenuation transitions



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Table 2. Recommended operating Condition

Parameter	Parameter		Condition	Min	Тур	Max	Unit
Supply Voltages	Supply Voltages			2.7		5.5	V
Supply Current	Supply Current				200	310	μΑ
Digital Control Input	High	V _{CTLH}	V _{DD} =3.3V or 5V	1.17		3.6	V
Digital Control Input	Low	V _{CTLL}	V _{DD} =3.3V or 5V	-0.3		0.6	V
Operating Temperature	Range	T_{case}	Exposed Paddle	-40		105	°C
RF Max Input Powe	RF Max Input Power		RF1 or RF2, CW			23	dBm
Impedance		Z_{Load}	Single ended		50		Ω

Specifications are not guaranteed over all recommended operating conditions.

Table 3. Absolute Maximum Ratings

Parameter		Symbol	Min	Тур	Max	Unit
Supp	ly Voltage	V _{DD}	-0.3		5.5	V
Digital i	input voltage	V_{CTL}	-0.3		3.6	V
Maximum input power		P _{IN_CWMAX}			31	dBm
T	Storage	T _{ST}	-65		150	$^{\circ}$ C
Temperature	Reflow	T _R			260	$^{\circ}$ C
	HBM ¹	rcp.			±1000	V
ESD Sensitivity	ПОІУІ	ESD _{HBM}			(Class 1C)	V
	cp. 4 ²	ESD _{CDM}			±1000	.,
	CDM ²				(Class C4)	V

Operation of this device above any of these parameters may result in permanent damage.

^{1.} HBM : Human Body Model (JEDEC Standard JS-001-2017)

^{2.} CDM : Charged Device Model (JEDEC Standard JS-002-2018)

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Figure 3. Pin Configuration (Top View)

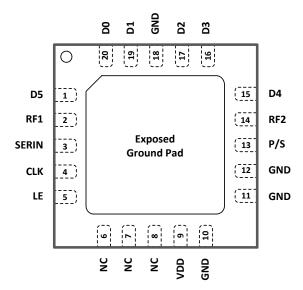


Table 4. Pin Description

Pin	Pin name	Description
1	D5 ²	Attenuation control bit, 16dB
2	RF1 ¹	RF1 port (Attenuator RF Input)
2	KFI	This pin can also be used as an output because the design is bi-directional. RF1 is dc-coupled and matched to 50 Ω
3	SERIN	Serial interface data input
4	CLK	Serial interface clock input
5	LE	Latch Enable input
6, 7, 8	NC	Not Connected
9	VDD	Power Supply (nominal 3.3V)
10, 11, 12, 18	GND	Ground, These pins must be connected to ground
13	P/S	Parallel/Serial Mode Select. For parallel mode operation, set this pin to LOW. For serial mode operation, set this pin to HIGH.
14	RF2 ¹	RF2 port (Attenuator RF Output.)
14	NF2	This pin can also be used as an input because the design is bi-directional. RF2 is dc-coupled and matched to 50 Ω .
15	D4 ²	Attenuation control bit, 8dB
16	D3 ²	Attenuation control bit, 4dB
17	D2 ²	Attenuation control bit, 2dB
19	D1 ²	Attenuation control bit, 1dB
20	DO ²	Attenuation control bit, 0.5dB
Pad	GND	Exposed pad: The exposed pad must be connected to ground for proper operation

^{1.} RF pins 2 and 14 must be at OV DC. The RF pins do not require DC blocking capacitors for proper Operation if the OV DC requirement is met

^{2.} Ground D0 - D5 if not in use or serial mode.



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Programming Options

BDA4620 can be programmed using either the parallel or serial interface, which is selectable via P/S pin(Pin13).

Serial mode is selected by pulling it to a voltage logic HIGH and parallel mode is selected by setting P/S to logic LOW

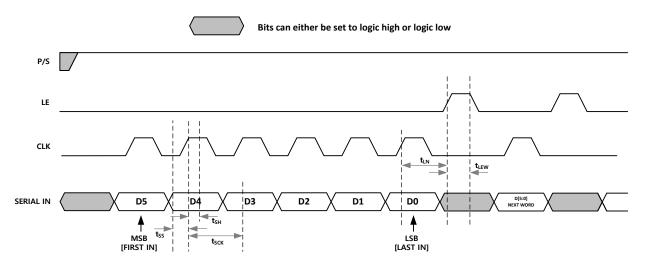
Serial Control Mode

The serial interface is a 6-bit shift register to shift in the data MSB (D5) first. When serial programming is used, It is recommended all the parallel control input pins (1, 15, 16, 17, 19, 20) are grounded. It is controlled by three CMOS-compatible signals: SERIN, Clock, and Latch Enable (LE).

Table 5. Truth Table for Serial Control Word

	Digital Control Input								
D5	D4	D3	D2	D1	D0	state			
(MSB)					(LSB)	(dB)			
LOW	LOW	LOW	LOW	LOW	LOW	0 (RL)			
LOW	LOW	LOW	LOW	LOW	HIGH	0.5			
LOW	LOW	LOW	LOW	HIGH	LOW	1			
LOW	LOW	LOW	HIGH	LOW	LOW	2			
LOW	LOW	HIGH	LOW	LOW	LOW	4			
LOW	HIGH	LOW	LOW	LOW	LOW	8			
HIGH	LOW	LOW	LOW	LOW	LOW	16			
HIGH	HIGH	HIGH	HIGH	HIGH	HIGH	31.5			

Figure 4. Serial Mode Timing Diagram



The BDA4620 has a 3-wire serial peripheral interface (SPI): serial data input (SERIN), clock (CLK), and latch enable (LE). The serial control interface is activated when P/S is set to HIGH.

In serial mode, the 6-bit Data is clocked MSB first on the rising CLK edges into the shift register and then LE must be toggled HIGH to latch the new attenuation state into the device. LE must be set to LOW to clock new 6-bit data into the shift register because CLK is masked to prevent the attenuator value from changing if LE is kept HIGH (see Figure 4 and Table 5).

Table 6. Serial Interface Timing Specifications

Symbol	Parameter		Тур	Max	Unit
f_{CLK}	Serial data clock frequency			10	MHz
t_{SCK}	Minimum serial period				ns
t _{ss}	Serial Data setup time	10			ns
t _{SH}	Serial Data hold time	10			ns
t _{LN}	LE setup time	10			ns
t _{LEW}	Minimum LE pulse width	30			ns

Table 7. Mode Selection

P/S	Control Mode
LOW	Parallel
HIGH	Serial

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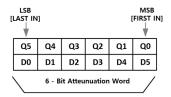


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Serial Register Map

The BDA4620 can be programmed via the serial control on the rising edge of Latch Enable (LE) which loads the last 6-bits data word in the SHIFT Register. Data is clocked in MSB(D5) first.

Figure 5. Serial Register Map

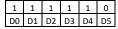


The attenuation word is derived directly from the value of the attenuation state. To find the attenuation word, multiply the value of the state by four, then convert to binary.

For example, to program the 15.5dB state:

2 x 15.5 = 31 31 -> 011111 D5-D0: 111110

Serial Input: 111110

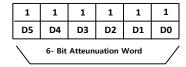


Power-UP states Settings

The BDA4620 will always initialize to the maximum attenuation setting (31.5 dB) on power-up for both the Serial and Latched Parallel modes of operation and will remain in this setting until the user latches in the next programming word.

In Direct Parallel mode, the DSA can be preset to any state within the 31.5 dB range by pre-setting the Parallel control pins prior to power-up. In this mode, there is a 400 µs delay between the time the DSA is powered-up to the time the desired state is set.

Figure 6. Default Register Settings





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Programming Options

Parallel Control Mode

The parallel control interface has seven digital control input lines (D5 to D0) to set the attenuation value. D5 is the most significant bit (MSB) that selects the 16 dB attenuator stage, and D0 is the least significant bit (LSB) that selects the 0.5 dB attenuator stage.

Direct Parallel Mode

For direct parallel mode, The LE pin must be kept HIGH. The attenuation state is changed by the control voltage inputs (D0 to D5) directly. This mode is ideal for manual control of the attenuator. In this mode the device will immediately react to any voltage changes to the parallel control pins [pins 1, 15, 16, 17, 19, 20]. Use direct parallel mode for the fastest settling time.

Latched Parallel Mode

The LE pin must be kept LOW when changing the control voltage inputs (D0 to D5) to set the attenuation state. When the desired state is set, LE must be toggled HIGH to transfer the 6-bit data to the bypass switches of the attenuator array, and then toggled LOW to latch the change into the device until the next desired attenuation change (see Figure 7 and Table 8).

- Set P/S is logic LOW.
- Set LE to logic LOW.
- Adjust pins [1, 15, 16, 17, 19, 20] to the desired attenuation setting. (Note the device will not react to these pins while LE is a logic LOW).
- Pull LE to a logic HIGH. The device will then transition to the attenuation settings reflected by pins D5 - D0.
- If LE is pulled to a logic LOW then the attenuator will not change state.

Latched Parallel Mode implies a default state for when the device is first powered up with P/S pin set for logic LOW and LE logic LOW. In this case the default setting is <u>Maximum attenuation</u>.

Table 8. Truth Table for the Parallel Control Word

D5	D4	D3	D2	D1	D0	P/S	LE	Attenuation State(dB)
LOW	LOW	LOW	LOW	LOW	LOW	LOW	HIGH	0 (RL)
LOW	LOW	LOW	LOW	LOW	HIGH	LOW	HIGH	0.5
LOW	LOW	LOW	LOW	HIGH	LOW	LOW	HIGH	1.0
LOW	LOW	LOW	HIGH	LOW	LOW	LOW	HIGH	2.0
LOW	LOW	HIGH	LOW	LOW	LOW	LOW	HIGH	4.0
LOW	HIGH	LOW	LOW	LOW	LOW	LOW	HIGH	8.0
HIGH	LOW	LOW	LOW	LOW	LOW	LOW	HIGH	16.0
HIGH	HIGH	HIGH	HIGH	HIGH	HIGH	LOW	HIGH	31.5

Figure 7. Latched Parallel Mode Timing Diagram

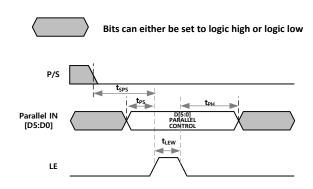


Table 9. Parallel Interface Timing Specifications

Symbol	Parameter	Min	Тур	Max	Unit
t _{SPS}	Serial to Parallel Mode Setup Time	100			ns
t _{LEW}	Minimum LE pulse width	10			ns
t _{PH}	Data hold time from LE				ns
t _{PS}	Data setup time to LE	10			ns

Switching Feature Description

Glitch-Safe Attenuation State Transient

The BDA4620 is the latest product applied *Glitch-Safe* technology with less than 1dB ringing (pos/neg) across the attenuation range when changing attenuation states. This technology protects Amplifiers or ADC during transitions between attenuation states. (see Figure 32,33).

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Typical RF Performance Plot - BDA4620 EVK - PCB

Typical Performance Data @ 25°C and V_{DD} = 3.3V, EV Kit RF connector and board losses are de-embedded, unless otherwise noted

Figure 8. Insertion loss vs Temperature

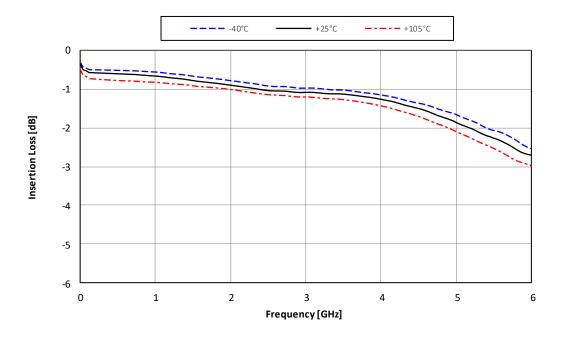
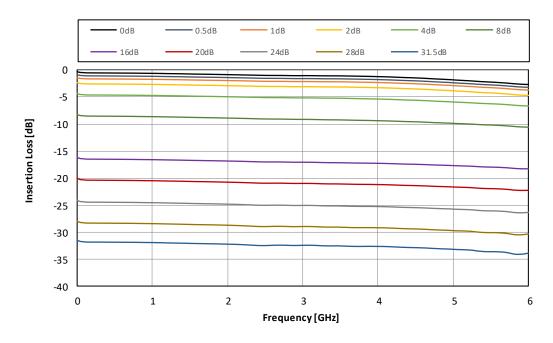


Figure 9. Insertion loss vs Attenuation Setting



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Figure 10. Input Return Loss vs Attenuation Setting

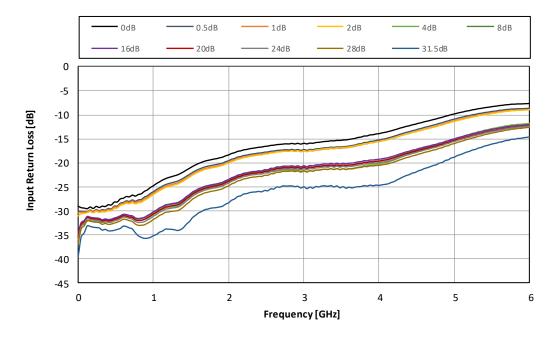
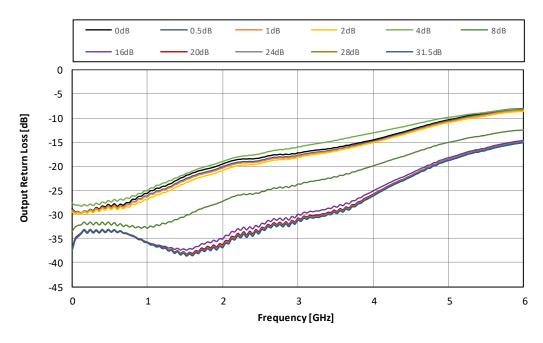


Figure 11. Output Return Loss vs Attenuation Setting



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Figure 12. Input Return Loss for 16dB Attenuation Setting vs Temperature

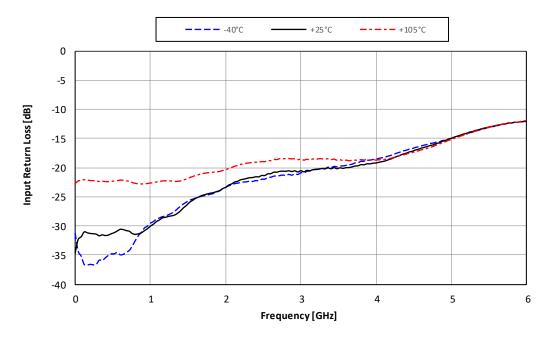
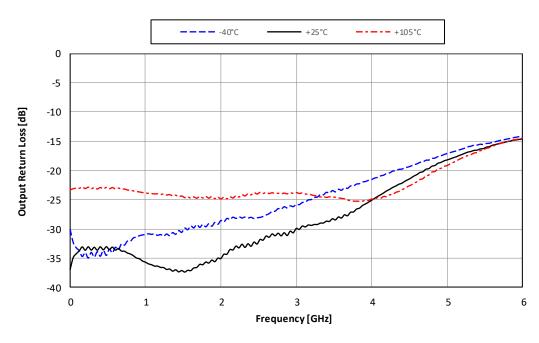


Figure 13. Output Return Loss for 16dB Attenuation Setting vs Temperature



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Typical Performance Data @ 25°C and V_{DD} = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 14. Relative Phase Error vs Attenuation Setting

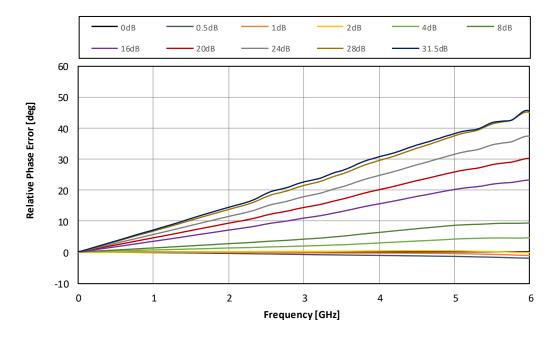
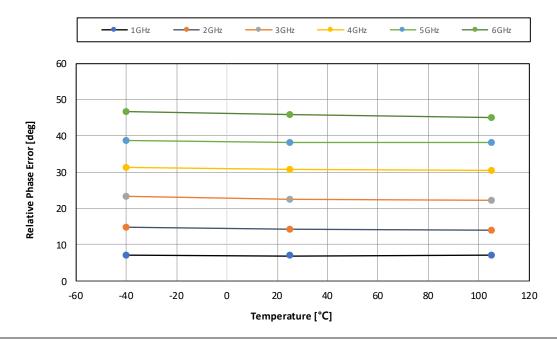


Figure 15. Relative Phase Error for 31.5dB Attenuation Setting vs Frequency



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Figure 16. Attenuation Error @900MHz vs Temperature

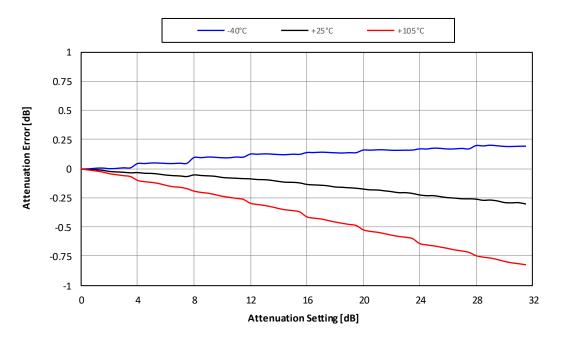
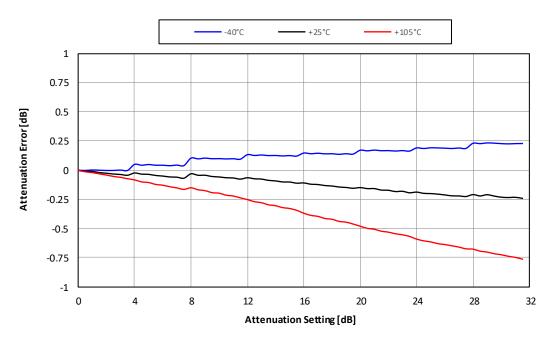


Figure 17. Attenuation Error @1800MHz vs Temperature



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Typical Performance Data @ 25°C and V_{DD} = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 18. Attenuation Error @2200MHz vs Temperature

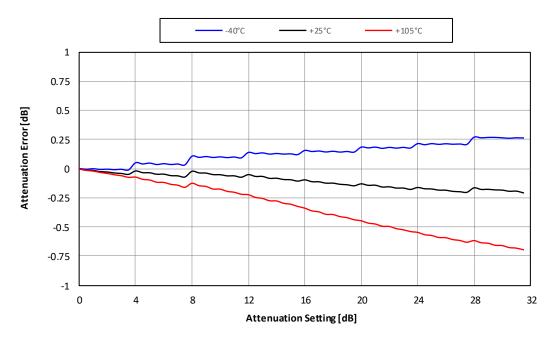
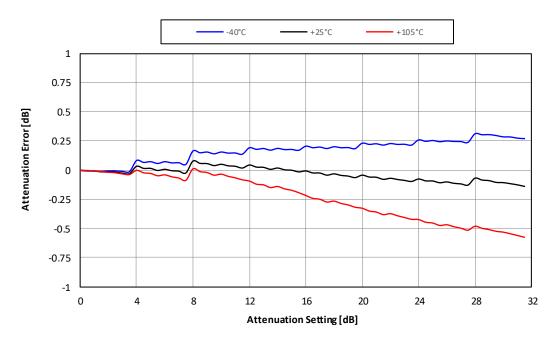


Figure 19. Attenuation Error @3500MHz vs Temperature



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Typical RF Performance Plot - BDA4620 EVK - PCB

Typical Performance Data @ 25°C and V_{DD} = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 20. Attenuation Error @4600MHz vs Temperature

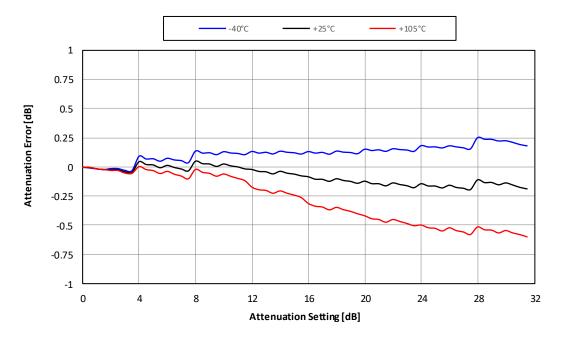
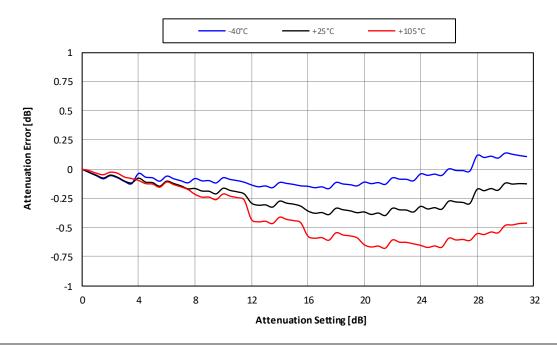


Figure 21. Attenuation Error @5800MHz vs Temperature



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Typical RF Performance Plot - BDA4620 EVK - PCB

Typical Performance Data @ 25°C and V_{DD} = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 22. IIP3 @ 2500MHz vs Temperature

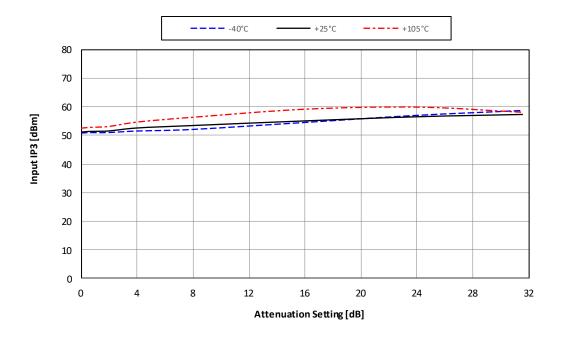
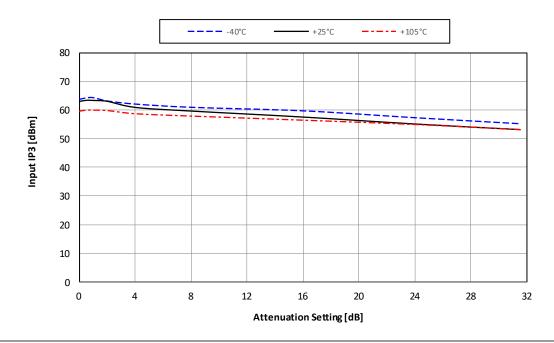


Figure 23. IIP3 @ 3500MHz vs Temperature



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1MHz - 6000MHz

Typical RF Performance Plot - BDA4620 EVK - PCB

Typical Performance Data @ 25°C and V_{DD} = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 24. IIP3 @ 4500MHz vs Temperature

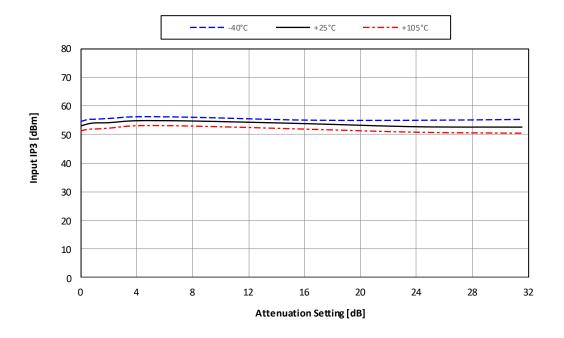
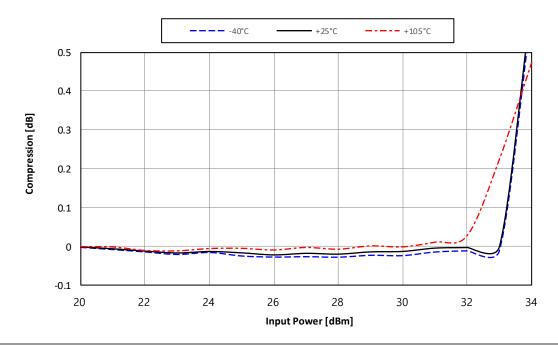


Figure 25. Input 0.1dB Compression @2500MHz vs Temperature



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1MHz - 6000MHz

Typical RF Performance Plot - BDA4620 EVK - PCB

Typical Performance Data @ 25°C and V_{DD} = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 26. Input 0.1dB Compression @3500MHz vs Temperature

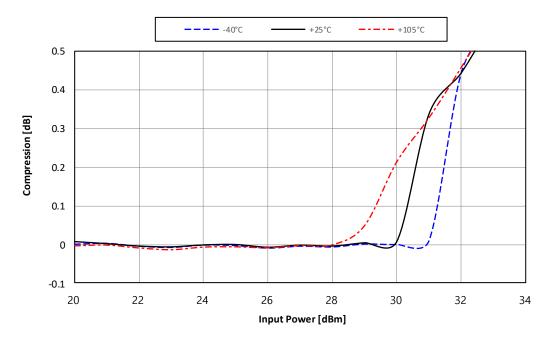
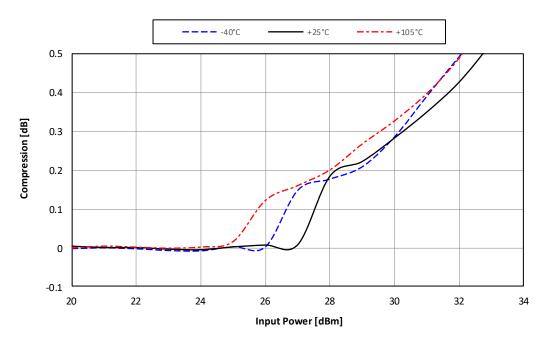


Figure 27. Input 0.1dB Compression @4500MHz vs Temperature



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1MHz - 6000MHz

Typical RF Performance Plot - BDA4620 EVK - PCB

Typical Performance Data @ 25°C and V_{DD} = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 28. 0.5dB Step Attenuation vs Frequency

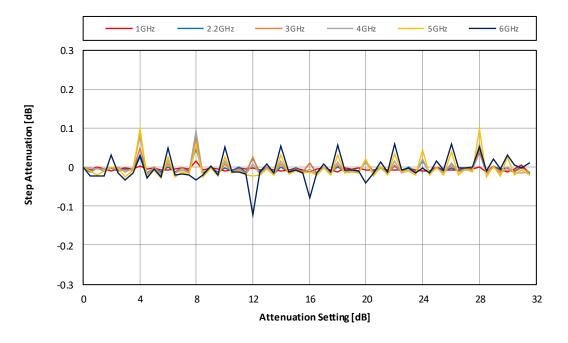
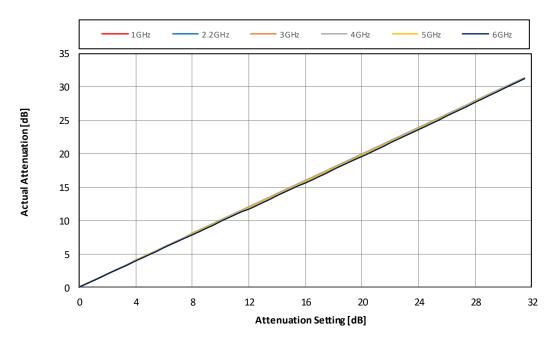


Figure 29. 0.5dB Step Attenuation vs Frequency



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Typical Performance Data @ 25°C and V_{DD} = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 30. Major State Bit Error vs Attenuation Setting

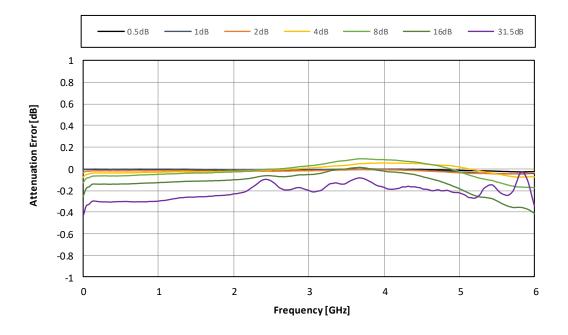
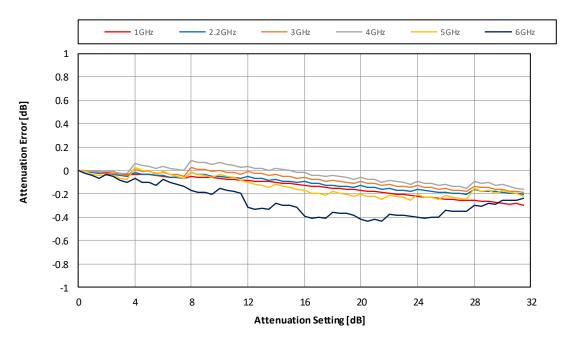


Figure 31. 0.5dB Step Attenuation Error vs Frequency



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1MHz - 6000MHz

Typical RF Performance Plot - BDA4620 EVK - PCB

Typical Performance Data @ 25°C and V_{DD} = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 32. Attenuation Transient (15.5 to 16dB, Pin=18dBm)

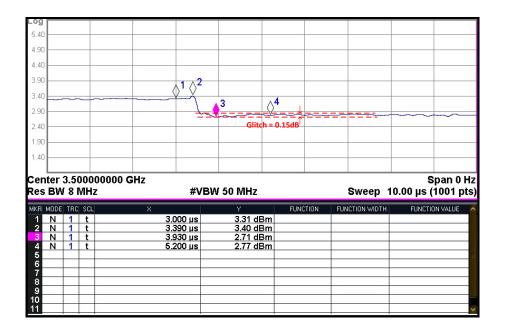
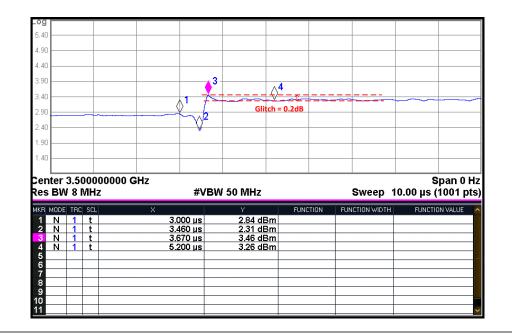


Figure 33. Attenuation Transient (16 to 15.5dB, Pin=18dBm)



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BDA4620 Evaluation board Kit Description



Figure 34. BDA4620 EVK

Evaluation board Kit Introduction

BDA4620 Evaluation Kit is made up of a combination of an RF board and an interface board

The schematic of the BDA4620 evaluation RF board is shown in Figure 34. The BDA4620 evaluation RF board is constructed of a 4-layer material with a copper thickness of 0.7 mils on each layer. Every copper layer is separated with a dielectric material. The top dielectric material is 8 mils RO4003. The middle and bottom dielectric materials are FR-4, used for mechanical strength and overall board thickness of approximately 1.63mm.

BDA4620 Evaluation INTERFACE board is assembled with a SP3T switches(D0~D5,LE), SP2T

BDA4620 Evaluation INTERFACE board is assembled with a SP3T switches(D0~D5,LE), SP2T mechanical switch (P/S), and several header & switch.

Evaluation Board Programming Using USB Interface

In order to evaluate the BDA4620 performance, the Application Software has to be installed on your computer. And The DSA application software GUI supports Latched Parallel and Serial modes. software can be downloaded from BeRex's website

Serial Control Mode

- Connect directly the Evaluation INTEFRACE board USB port(J3) to PC
- Set the direction of P<->S Switch to S direction (P/S Logic HIGH)
- Set the D0~D5, LE switch to the middle position.
- Operate the 0~31.5dB attenuation state in GUI and then control the DSA

Latched Parallel Control Mode

- Connect directly the Evaluation INTEFRACE board USB port(J3) to PC
- Set the direction of P<->S Switch to P direction (P/S Logic LOW)
- Set the D0~D5, LE switch to the middle position.
- Operate the 0~31.5dB attenuation state in GUI and then control the DSA

Direct Parallel Control Mode

- Set the direction of P<->S Switch to P direction (P/S Logic LOW)
- Set LE switch to the LOW Position
- For the setting to attenuation state, D0~D5 switches can be combined in manually program, refer to Table 9.

Please refer to user manual for more detailed operation method of BDA4620 EVK.

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BDA4620 Evaluation board Kit Description

Figure 35. Evaluation Board Kit Schematic Diagram

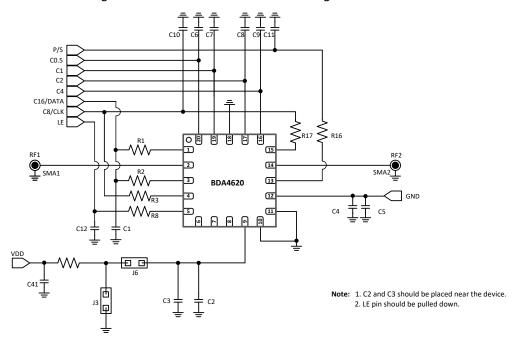


Figure 36. Evaluation Board PCB Layout Information 50Ω

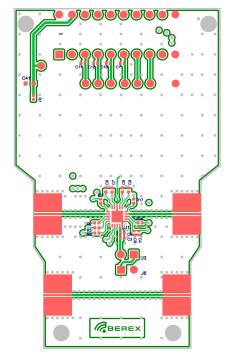
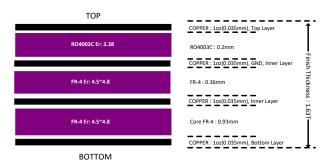


Table 10. Bill of Material - Evaluation Board

No.	Ref Des	Part Qty	Value	Description	Remark
1	C1,C2,C6-C12	9	100pF	CAP, 0402, CHIP Ceramic, ±0.25%	
2	C3	1	100nF	CAP, 0402, CHIP Ceramic, ±0.25%	
3	R1,R16,C4	3	0 ohm	RES, 0402, CHIP, ±5%	
4	R2,R3,R8,R17	4	1k ohm	RES, 0402, CHIP, ±5%	
5	SMA1, SMA2	2	CON	SMA END LAUNCH	
6	U1	1	Chip	DSA, BDA4620 QFN4x4 24L	

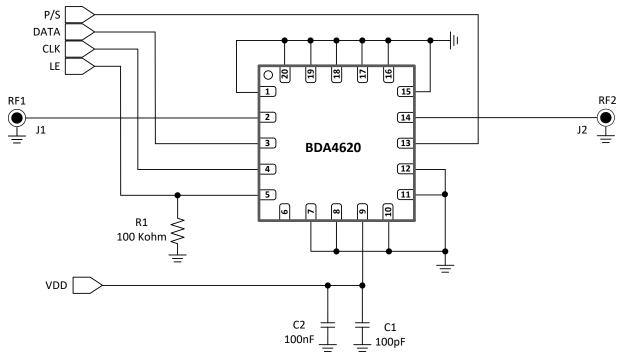
Figure 37. Evaluation Board PCB Layer Information 50Ω



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Figure 38. Recommended Serial mode Application Circuit Schematic

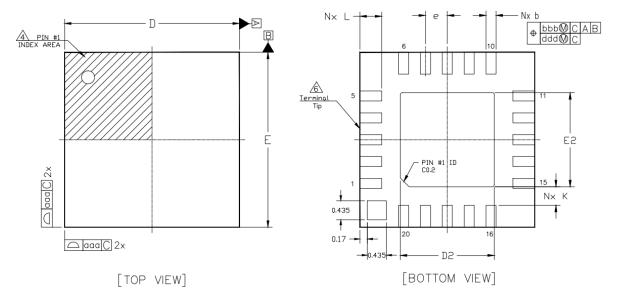


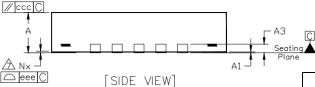
Note: 1. C1 and C2 should be placed near the device.

2. Recommended to add pull-down resistor(R1) at the LE pin.

1MHz - 6000MHz

Figure 39. Packing Outline Dimension





NOTE:

- 1. Dimensioning and tolerancing conform to ASME Y14.5-2009.
- 2. All dimensions are in millimeters.
- 3. N is the total number of terminals.
- 4. The location of the marked terminal #1 identifier is within the hatched area.
- 5. ND and NE refer to the number of terminals on each D and E side respectively.
- 6. Dimension b applies to the metallized terminal and is measured between 0.15mm and 0.30mm from the terminal tip. If the terminal has a radius on the other end of it, dimension b should not be measured in that radius area.
- 7. Coplanarity applies to the terminals and all other bottom surface metallization

	Dimension Table								
Cumbal		NOTE							
Symbol	MINIMUM	NOMINAL	MAXIMUM	NOTE					
Α	0.80	0.90	1.00						
A1	0.00	0.02	0.05						
A3		0.203 Ref							
b	0.18	0.23	0.28	6					
D		4.00 BSC							
E		4.00 BSC							
е		0.50 BSC							
D2	2.10	2.15	2.20						
E2	2.10	2.15	2.20						
K	0.20								
L	0.45	0.55	0.65						
aaa		0.05							
bbb		0.10							
ссс		0.10							
ddd		0.05							
eee		0.08							
N		20		3					
ND		5		5					
NE		5		5					

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Figure 40. Recommend Land Pattern

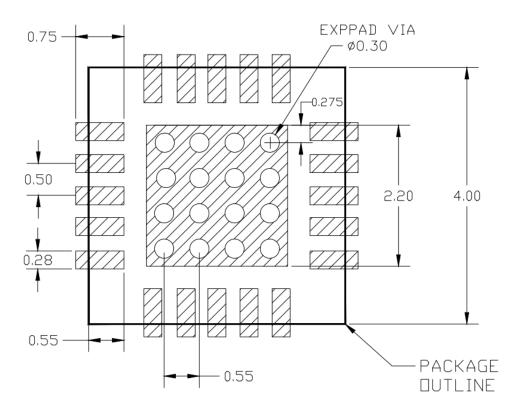


Figure 41. Package Marking

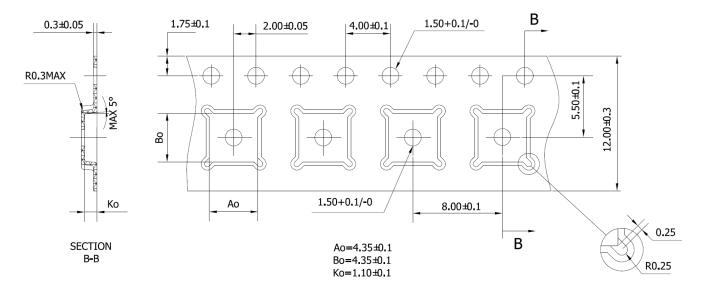


Marking information:				
BDA4620	Device Name			
YY	Year			
ww	Work Week			
XX	LOT Number			



1MHz - 6000MHz

Figure 42. Tape & Reel



- NOTES: 1.10 SPROCKET HOLE PITCH CUMULATIVE TOLERANCE ±0,2 2 CAMBER IN COMPLANCE WITH EIA 481 3 POCKET POSITION RELATIVE TO SPROCKET HOLE MEASURED AS TRUE POSITION OF POCKET, NOT POCKET HOLE

Packaging information:	
Tape Width	12mm
Reel Size	7inch
Device Cavity Pitch	8mm
Devices Per Reel	1k



1MHz - 6000MHz

Lead plating finish

100% Tin Matte finish

(All BeRex products undergoes a 1 hour, 150 degree C, Anneal bake to eliminate thin whisker growth concerns.)

MSL / ESD Rating

ESD Rating: Class 1C **Value:** $\pm 1000V$

Test: Human Body Model (HBM)
Standard: JEDEC Standard JS-001-2017

ESD Rating: Class C3
Value: ±1000V

Test: Charged Device Model (CDM)
Standard: JEDEC Standard JESD22-C101F

MSL Rating: Level 1 at +260°C convection reflow

Standard: JEDEC Standard J-STD-020



Proper ESD procedures should be followed when handling this device.

RoHS Compliance

This part is compliant with Restrictions on the use of certain Hazardous Substances in Electrical and Electronic Equipment (RoHS) Directive 2011/65/EU as amended by Directive 2015/863/EU.

This product also is compliant with a concentration of the Substances of Very High Concern (SVHC) candidate list which are contained in a quantity of less than 0.1%(w/w) in each components of a product and/or its packaging placed on the European Community market by the BeRex and Suppliers.

NATO CAGE code:

2 N 9 6 F	
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