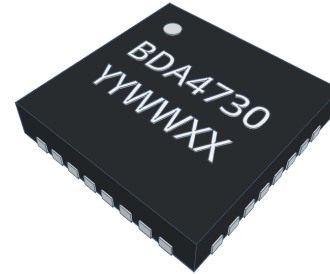


### Device Features

- 7-bit Serial & Parallel Interface
- 31.75 dB Control Range 0.25 dB step
- Support addressable Function (Addr0-Addr7)
- Glitch-safe attenuation state transitions
- 2.5 V to 5.5 V supply
- Excellent Attenuation Accuracy
  - ±(0.15 + 1.5% of attenuation state) @ 1.9GHz
  - ±(0.25 + 3.5% of attenuation state) @ 3.5GHz
  - ±(0.25 + 7.0% of attenuation state) @ 7.2GHz
- Low Insertion Loss
  - 0.8 dB @ 1.9GHz
  - 1.2 dB @ 3.5GHz
  - 2.7 dB @ 7.2GHz
- Ultra linearity IIP3 > +68 dBm @ 3.5GHz, ATT=0dB
- Input 0.1dB Compression (P0.1dB) 30dBm @ 3.5GHz, ATT=0dB
- Programming modes
  - Direct parallel
  - Latched parallel
  - Serial Addressable
- Stable Integral Non-Linearity over temperature
- Low Current Consumption 200 µA typical
- -40 °C to +105 °C operating temperature
- ESD rating : Class1C (1kV HBM)
- Lead-free/RoHS2-compliant 32-lead 5mm x 5mm x 0.9mm QFN SMT package



32-lead 5mm x 5 mm x 0.9mm QFN

Figure 1. Package Type

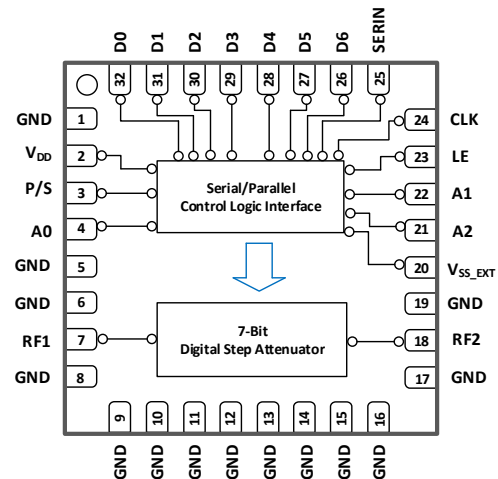


Figure 2. Functional Block Diagram

### Product Description

The BDA4730 is a broadband, Highly accurate 50Ω digital step attenuator model which provides adjustable attenuation from 0 to 31.75 dB in 0.25 dB steps. The control interface supports a 7-bit serial interface with 3-bit addressable function and latched parallel interface.

The BDA4730 has an optional function of using a negative voltage through V<sub>SS\_EXT</sub> pin for improved spurious performance. This option is an optimized function that can be applied to test and measurement equipment.

BDA4730 supports a broad operating frequency range from 9kHz to 9.0 GHz. BDA4730 is offering the High linearity, low power consumption, low insertion loss, high attenuation accuracy and low insertion loss, typically less than 2.9dB up to 8.5GHz.

The device features a safe state transitions with no negative/positive Glitch technology optimized for excellent step accuracy.

Basically the RF input and output are internally matched to 50 Ω and do not require any external matching components. In some cases to optimize Return loss for above 4 - 8.5GHz, Shunt capacitor can be added near RF1 and RF2 respectively. The design is bi-directional; Therefore, the RF input and output are interchangeable.

The BDA4730 does not require blocking capacitors. If DC is presented at the RF port, add a blocking capacitor. This is packaged in a RoHS2-compliant with QFN surface mount package.

### Application

- 6G/5G/4G/3G Cellular Base station/Repeater Infrastructure
- Test and measurement (T&M)
- Digital Pre-Distortion
- Distributed Antenna Systems, DAS
- Remote Radio Heads
- NFC Infrastructure
- Test Equipment and sensors
- Military Wireless system
- Cable Infrastructure
- General purpose Wireless

**7-bit Digital Step Attenuator with Addressable Function**
**9kHz – 9000MHz**
**Table 1. Electrical Specifications**

Specifications are performance on the BeRex EVKit at VDD=3.3V, 25°C, 50Ω system. Performance were measured based on Typical application circuits Table 13. ( See the Page 9 )

| Parameter                   | Condition  | Frequency  | Min    | Typ                                      | Max                                      | Unit   |
|-----------------------------|--|--|--------|--|--|--------|
| Frequency Range             |  |  | 0.009  |  | 8000                                     | MHz    |
| Attenuation range           | 0.25dB step  |  |        | 0 - 31.75                                |  | dB     |
| Insertion Loss <sup>1</sup> | ATT = 0dB  | 9kHz - 1GHz  |        | 0.6                                      | 0.7                                      | dB     |
|                             |  | 1 - 2GHz   |        | 0.7                                      | 0.8                                      | dB     |
|                             |  | 2 - 4GHz   |        | 1.1                                      | 1.4                                      | dB     |
|                             |  | 4 - 6GHz   |        | 2.0                                      | 2.7                                      | dB     |
|                             |  | 6 - 8GHz   |        | 2.8                                      | 2.8                                      | dB     |
| Attenuation Error           | 0.25dB Step  |  |        |  |  |        |
|                             | 0-31.75dB  | 9kHz - 2GHz  |        |  | $\pm(0.15 + 1.5\%$ of attenuation state) | dB     |
|                             |  | 2 - 3GHz   |        |  | $\pm(0.15 + 2.5\%$ of attenuation state) |        |
|                             |  | 3 - 5GHz   |        |  | $\pm(0.25 + 3.5\%$ of attenuation state) |        |
|                             |  | 5 - 6GHz   |        |  | $\pm(0.25 + 5.0\%$ of attenuation state) |        |
|                             | 1dB Step   |  |        |  |  |        |
|                             | 0-31.0dB   | 9kHz - 2GHz  |        |  | $\pm(0.15 + 1.5\%$ of attenuation state) | dB     |
|                             |  | 2 - 3GHz   |        |  | $\pm(0.15 + 2.5\%$ of attenuation state) |        |
|                             |  | 3 - 5GHz   |        |  | $\pm(0.25 + 3.5\%$ of attenuation state) |        |
|                             |  | 5 - 6GHz   |        |  | $\pm(0.25 + 5.0\%$ of attenuation state) |        |
| 6 - 8GHz                    |  |  |        | $\pm(0.25 + 7.0\%$ of attenuation state) |  |        |
| Input Return Loss           | ATT = 0dB  | 1 - 4GHz   |        | 20                                       |  | dB     |
|                             |  | 4 - 8GHz   |        | 9  |  |        |
| Output Return Loss          | ATT = 0dB  | 1 - 4GHz   |        | 21                                       |  | dB     |
|                             |  | 4 - 8GHz   |        | 9  |  |        |
| Relative Phase Error        | All States   | 1GHz   |        | 7  |  | degree |
|                             |  | 2GHz   |        | 14                                       |  |        |
|                             |  | 3GHz   |        | 22                                       |  |        |
|                             |  | 4GHz   |        | 31                                       |  |        |
|                             |  | 5GHz   |        | 39                                       |  |        |
|                             |  | 6GHz   |        | 47                                       |  |        |
| Input Linearity             | Input 0.1dB Compression point  | ATT = 0dB  | 3.5GHz |  | 30                                       | dBm    |
|                             |  | Pin = +18dBm/tone, $\Delta f = 20$ MHz<br>ATT = 0.0dB<br>RF Input = RF1 Port | 2.5GHz |  | 63                                       |        |
|                             | 3.5GHz   |  |        | 68                                       |  |        |
|                             | 4.5GHz   |  |        | 59                                       |  |        |
|                             | 7.25GHz  |  |        | 52                                       |  |        |
|                             | Pin = +18dBm/tone, $\Delta f = 20$ MHz<br>ATT = 31.75dB<br>RF Input = RF1 Port | 2.5GHz   |        | 59                                       |  |        |
|                             |  | 3.5GHz   |        | 58                                       |  |        |
|                             |  | 4.5GHz   |        | 54                                       |  |        |
|                             |  | 7.25GHz  |        | 51                                       |  |        |
|                             | Pin = +18dBm/tone, $\Delta f = 20$ MHz<br>ATT = 0.0dB<br>RF Input = RF2 Port   | 2.5GHz   |        | 64                                       |  |        |
|                             |  | 3.5GHz   |        | 60                                       |  |        |
|                             |  | 4.5GHz   |        | 58                                       |  |        |
|                             |  | 7.25GHz  |        | 49                                       |  |        |
|                             | Pin = +18dBm/tone, $\Delta f = 20$ MHz<br>ATT = 31.75dB<br>RF Input = RF2 Port | 2.5GHz   |        | 58                                       |  |        |
| 3.5GHz                      |  |  | 57     |  |  |        |
| 4.5GHz                      |  |  | 56     |  |  |        |
| 7.25GHz                     |  |  | 42     |  |  |        |

## 7-bit Digital Step Attenuator with Addressable Function

9kHz – 9000MHz

**Table 1. Electrical Specifications (Cont.)**

| Parameter                                     | Condition  | Frequency          | Min | Typ    | Max | Unit     |
|---|--|--------------------|-----|--------|-----|----------|
| RF Rising / Falling Time                      | 10%/90% RF   | 2GHz               |     | 121    |     | ns       |
| Switching time                                | 50% CTRL to 90% or 10% RF  | 2GHz               |     | 224    |     | ns       |
| Settling time                                 | 50% CTRL to Max or Min Attenuation to settle within 0.05 dB of final value | 2GHz               |     | 500    |     | ns       |
| Attenuation Transient (envelope) <sup>2</sup> | Positive glitch, Any ATT step  | 3.5GHz             |     | 0.3    |     | dB       |
| Maximum Spurious level                        | Measured at RF1 and RF2 port   | 9kHz - 5MHz        |     | -142   |     | dBm/10Hz |
|   |  | >5MHz <sup>3</sup> |     | < -145 |     |          |

1. The Evaluation board Kit insertion loss (PCB & RF Connector) is de-embedded.

2. Attenuation Transient is glitch level due to attenuation transitions

3. No spurious signals were detected above 5MHz.

**Table 2. Electrical Specifications<sup>1</sup> ( Optimized Return Loss Application )**

Specifications are performance on the BeRex EVKit at VDD=3.3V, 25°C, 50 Ω system. Performance were measured based on Optimized Return Loss Application Circuits Table 14. ( See the Page 16 )

| Parameter                   | Condition               | Frequency   | Min   | Typ       | Max                                 | Unit   |
|-----------------------------|-------------------------|-------------|-------|-----------|-------------------------------------|--------|
| Frequency Range             |                         |             | 0.009 |           | 9000                                | MHz    |
| Attenuation range           | 0.25dB step             |             |       | 0 - 31.75 |                                     | dB     |
| Insertion Loss <sup>2</sup> | ATT = 0dB               | 9kHz - 1GHz |       | 0.6       |                                     | dB     |
|                             |                         | 1 - 2GHz    |       | 0.8       |                                     | dB     |
|                             |                         | 2 - 3GHz    |       | 0.9       |                                     | dB     |
|                             |                         | 3 - 4GHz    |       | 1.0       |                                     | dB     |
|                             |                         | 4 - 6GHz    |       | 1.7       |                                     | dB     |
|                             |                         | 6 - 8GHz    |       | 2.2       |                                     | dB     |
|                             |                         | 8 - 9GHz    |       | 3.8       |                                     | dB     |
| Attenuation Error           | 0-31.75dB / 0.25dB Step | 9kHz - 2GHz |       |           | ±(0.15 + 1.5% of attenuation state) | dB     |
|                             |                         | 2 - 3GHz    |       |           | ±(0.15 + 2.5% of attenuation state) | dB     |
|                             |                         | 3 - 4GHz    |       |           | ±(0.25 + 3.5% of attenuation state) | dB     |
|                             |                         | 4 - 6GHz    |       |           | ±(0.25 + 5.0% of attenuation state) | dB     |
|                             |                         | 6 - 9GHz    |       |           | ±(0.35 + 7.0% of attenuation state) | dB     |
| Input Return Loss           | ATT = 0dB               | 1 - 4GHz    |       | 19        |                                     | dB     |
|                             |                         | 4 - 6GHz    |       | 16        |                                     |        |
|                             |                         | 6 - 9GHz    |       | 18        |                                     |        |
| Output Return Loss          | ATT = 0dB               | 1 - 4GHz    |       | 20        |                                     | dB     |
|                             |                         | 4 - 6GHz    |       | 16        |                                     |        |
|                             |                         | 6 - 9GHz    |       | 17        |                                     |        |
| Relative Phase Error        | All states              | 1GHz        |       | 7         |                                     | degree |
|                             |                         | 2GHz        |       | 13        |                                     |        |
|                             |                         | 3GHz        |       | 21        |                                     |        |
|                             |                         | 4GHz        |       | 29        |                                     |        |
|                             |                         | 5GHz        |       | 37        |                                     |        |
|                             |                         | 6GHz        |       | 45        |                                     |        |
|                             |                         | 7GHz        |       | 54        |                                     |        |
|                             |                         | 8GHz        |       | 67        |                                     |        |
| 9GHz                        |                         | 78          |       |           |                                     |        |

1. In order to improve Return loss above 4GHz, shunt capacitor 0.1pF was added to each RF1 & RF2. ( See Optimized Return loss application circuits Table 14 on page 16 )

2. The Evaluation board Kit insertion loss (PCB & RF Connector) is de-embedded.

**Table 3. Recommended Operating Condition**

| Parameter  | Symbol             | Condition         | Min                         | Typ  | Max  | Unit |   |
|--|--------------------|-------------------|-----------------------------|------|------|------|---|
| <b>Normal State (V<sub>SS_EXT</sub> pin = Ground)</b>    |                    |                   |                             |      |      |      |   |
| Supply Voltage   | V <sub>DD</sub>    |                   | 2.5                         |      | 5.5  | V    |   |
| Supply Current   | I <sub>DD</sub>    |                   |                             | 200  | 350  | μA   |   |
| <b>External Vss State (V<sub>SS_EXT</sub> pin = Vss)</b> |                    |                   |                             |      |      |      |   |
| Supply Voltage   | V <sub>DD</sub>    |                   | 2.5                         |      | 5.5  | V    |   |
| Supply Current   | I <sub>DD</sub>    |                   |                             | 100  | 200  | μA   |   |
| Negative Supply Voltage                                  | V <sub>SS</sub>    |                   | -2.7                        |      | -2.3 | V    |   |
| Negative Supply Current                                  | I <sub>SS</sub>    |                   |                             | -3   |      | μA   |   |
| <b>Common (Normal and External Vss State)</b>            |                    |                   |                             |      |      |      |   |
| Digital Control Input                                    | High               | V <sub>CTLH</sub> | V <sub>DD</sub> =3.3V or 5V | 1.17 |      | 3.6  | V |
|  | Low                | V <sub>CTLL</sub> | V <sub>DD</sub> =3.3V or 5V | -0.3 |      | 0.6  | V |
| Operating Temperature Range                              | T <sub>Case</sub>  | Exposed Paddle    | -40                         |      | 105  | °C   |   |
| RF Max Input Power                                       | P <sub>IN_CW</sub> | RF1 or RF2, CW    |                             |      | 23   | dBm  |   |
| Impedance  | Z <sub>Load</sub>  | Single ended      |                             | 50   |      | Ω    |   |

**Table 4. Absolute Maximum Ratings**

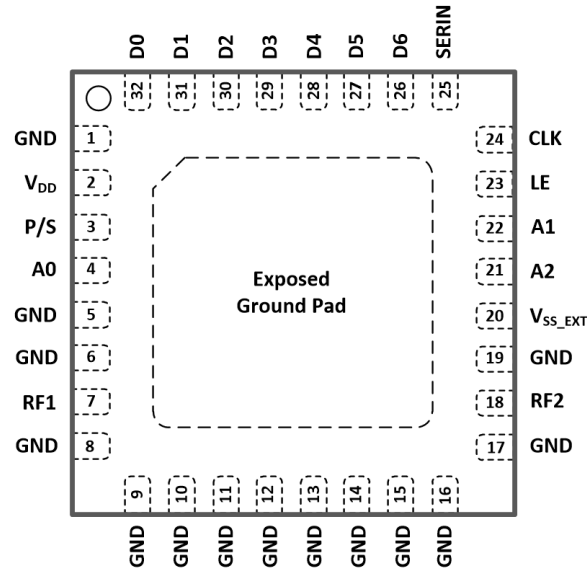
| Parameter             | Symbol                | Min                | Typ | Max | Unit                |    |
|-----------------------|-----------------------|--------------------|-----|-----|---------------------|----|
| Supply Voltage        | V <sub>DD</sub>       | -0.3               |     | 5.5 | V                   |    |
| Digital Input Voltage | V <sub>CTL</sub>      | -0.3               |     | 3.6 | V                   |    |
| Maximum Input Power   | P <sub>IN_CWMAX</sub> |                    |     | 31  | dBm                 |    |
| Temperature           | Storage               | T <sub>ST</sub>    | -65 |     | 150                 | °C |
|                       | Reflow                | T <sub>R</sub>     |     |     | 260                 | °C |
| ESD Sensitivity       | HBM <sup>1</sup>      | ESD <sub>HBM</sub> |     |     | ±1000<br>(Class 1C) | V  |
|                       | CDM <sup>2</sup>      | ESD <sub>CDM</sub> |     |     | ±1000<br>(Class C3) | V  |

Operation of this device above any of these parameters may result in permanent damage.

1. HBM : Human Body Model (JEDEC Standard JS-001-2017)
2. CDM : Charged Device Model (JEDEC Standard JS-002-2018)

**Table 5. Package Thermal Characteristics**

| Parameter                              | Symbol          | Value | Unit |
|--|-----------------|-------|------|
| Junction to Ambient Thermal Resistance | θ <sub>JA</sub> | 30.2  | °C/W |

**Figure 3. Pin Configuration (Top View)**

**Table 6. Pin Description**

| Pin               | Pin name                         | Description   |
|-------------------|----------------------------------|---|
| 1, 5, 6, 8-17, 19 | GND                              | Ground, These pins must be connected to ground  |
| 2                 | VDD                              | Power Supply (nominal 3.3V)   |
| 3                 | P/S                              | Parallel/Serial Mode Select. For parallel mode operation, set this pin to LOW. For serial mode operation, set this pin to HIGH.                       |
| 4                 | A0                               | Address bit A0 connection.  |
| 7                 | RF1 <sup>1</sup>                 | RF1 port (Attenuator RF Input)<br>This pin can also be used as an output because the design is bidirectional. RF1 is dc-coupled and matched to 50 Ω   |
| 18                | RF2 <sup>1</sup>                 | RF2 port (Attenuator RF Output.)<br>This pin can also be used as an input because the design is bidirectional. RF2 is dc-coupled and matched to 50 Ω. |
| 20                | V <sub>SS_EXT</sub> <sup>3</sup> | External VSS negative voltage control. If not use the externally negative voltage, This pin must be Ground.   |
| 21                | A2                               | Address bit A2 connection.  |
| 22                | A1                               | Address bit A1 connection.  |
| 23                | LE                               | Latch Enable input  |
| 24                | CLK                              | Serial interface clock input  |
| 25                | SERIN                            | Serial interface data input   |
| 26                | D6 <sup>2</sup>                  | Parallel Control Voltage Inputs, Attenuation control bit 16dB   |
| 27                | D5 <sup>2</sup>                  | Parallel Control Voltage Inputs, Attenuation control bit 8dB  |
| 28                | D4 <sup>2</sup>                  | Parallel Control Voltage Inputs, Attenuation control bit 4dB  |
| 29                | D3 <sup>2</sup>                  | Parallel Control Voltage Inputs, Attenuation control bit 2dB  |
| 30                | D2 <sup>2</sup>                  | Parallel Control Voltage Inputs, Attenuation control bit 1dB  |
| 31                | D1 <sup>2</sup>                  | Parallel Control Voltage Inputs, Attenuation control bit 0.5dB  |
| 32                | D0 <sup>2</sup>                  | Parallel Control Voltage Inputs, Attenuation control bit 0.25dB   |
| Pad               | GND                              | Exposed pad: The exposed pad must be connected to ground for proper operation   |

1. RF pins 7 and 18 must be at 0V DC. The RF pins do not require DC blocking capacitors for proper Operation if the 0V DC requirement is met

2. It is recommended to ground the D0 ~ D6 in serial mode.

3. Connect V<sub>SS\_EXT</sub> (pin 20) to GND (V<sub>SS\_EXT</sub> = 0V) to enable internal negative voltage generator, And use V<sub>SS\_EXT</sub> (pin 20) to bypass and disable internal negative voltage generator.

### Programming Options

BDA4730 can be programmed using either the parallel or serial interface, which is selectable via P/S pin(Pin3).

Serial mode is selected by pulling it to a voltage logic HIGH and parallel mode is selected by setting P/S to logic LOW

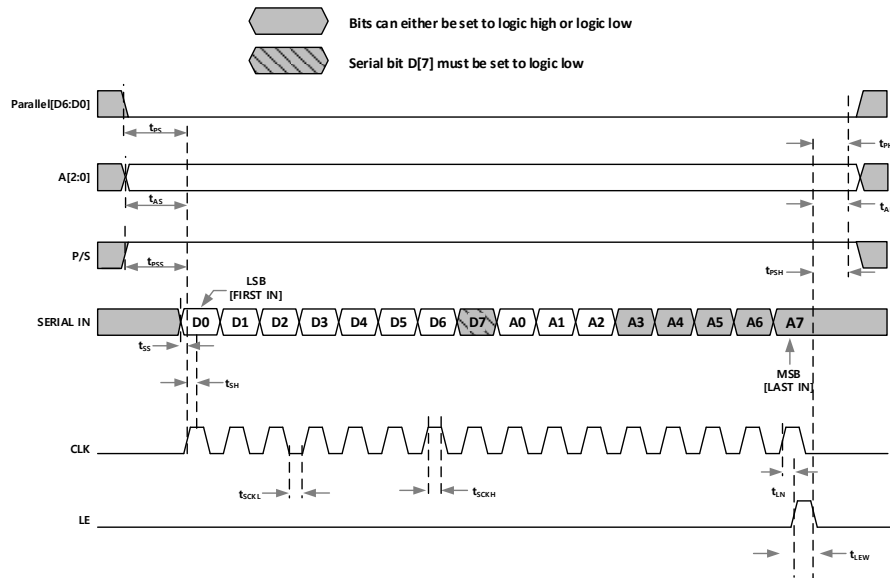
### Serial Control Mode

The serial interface is a 16-bit shift register to shift in the data LSB (D0) first. When serial programming is used, It is recommended all the parallel control input pins (26, 27, 28, 29, 30, 31, 32) are grounded. It is controlled by three CMOS-compatible signals: SERIN, Clock, and Latch Enable (LE).

**Table 7. Truth Table for Serial Control Word**

| Digital Control Input |      |      |      |      |      |      |          | Attenuation state (dB) |
|-----------------------|------|------|------|------|------|------|----------|------------------------|
| D7 (MSB)              | D6   | D5   | D4   | D3   | D2   | D1   | D0 (LSB) |                        |
| LOW                   | LOW  | LOW  | LOW  | LOW  | LOW  | LOW  | LOW      | 0 (RL)                 |
| LOW                   | LOW  | LOW  | LOW  | LOW  | LOW  | LOW  | HIGH     | 0.25                   |
| LOW                   | LOW  | LOW  | LOW  | LOW  | LOW  | HIGH | LOW      | 0.5                    |
| LOW                   | LOW  | LOW  | LOW  | LOW  | HIGH | LOW  | LOW      | 1.0                    |
| LOW                   | LOW  | LOW  | LOW  | HIGH | LOW  | LOW  | LOW      | 2.0                    |
| LOW                   | LOW  | LOW  | HIGH | LOW  | LOW  | LOW  | LOW      | 4.0                    |
| LOW                   | LOW  | HIGH | LOW  | LOW  | LOW  | LOW  | LOW      | 8.0                    |
| LOW                   | HIGH | LOW  | LOW  | LOW  | LOW  | LOW  | LOW      | 16.0                   |
| LOW                   | HIGH | HIGH | HIGH | HIGH | HIGH | HIGH | HIGH     | 31.75                  |

**Figure 4. Serial Mode Timing Diagram**



BDA4730 Serial mode is selected by pulling it to logic HIGH. The serial interface is a 16-bit shift register made up of two words. The first 8-bit word is the Attenuation word, which controls the DSA state. The second word is the address word, which uses only 3 of 8-bits that must match the hard wired A0-A2 programming in order to change the DSA state. If no external connections are made to A0 – A2 then internally they will default to 000 due to internal pull down resistors. If these 3 external preset address bits are not matched with the SPI loaded address bits then the current attenuator state will remain unchanged. This allows up to 8 serial-controlled devices to be used on a single board, which share a common SERIN, CLK and LE.

When serial programming is used, all the parallel control input pins 26 – 32 can be left open or grounded.

**Table 8. Serial Interface Timing Specifications**

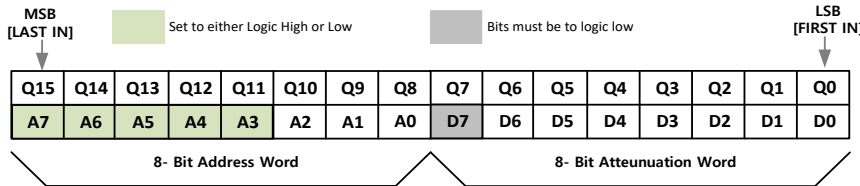
| Symbol     | Parameter                   | Min | Typ | Max | Unit |
|------------|-----------------------------|-----|-----|-----|------|
| $f_{CLK}$  | Serial data clock frequency |     |     | 10  | MHz  |
| $t_{PS}$   | Parallel data setup time    | 100 |     |     | ns   |
| $t_{PH}$   | Parallel data hold time     | 100 |     |     | ns   |
| $t_{AS}$   | Address setup time          | 100 |     |     | ns   |
| $t_{AH}$   | Address hold time           | 100 |     |     | ns   |
| $t_{PSS}$  | Parallel/Serial setup time  | 100 |     |     | ns   |
| $t_{PSH}$  | Parallel/Serial hold time   | 100 |     |     | ns   |
| $t_{SS}$   | Serial Data setup time      | 10  |     |     | ns   |
| $t_{SH}$   | Serial Data hold time       | 10  |     |     | ns   |
| $t_{SCKH}$ | Serial clock high time      | 30  |     |     | ns   |
| $t_{SCKL}$ | Serial clock low time       | 30  |     |     | ns   |
| $t_{LN}$   | LE setup time               | 10  |     |     | ns   |
| $t_{LEW}$  | Minimum LE pulse width      | 30  |     |     | ns   |

### Serial Register Map

The BDA4730 can be programmed via the serial control on the rising edge of Latch Enable (LE) which loads the last 8-bits attenuation word and 8-bits address word in the SHIFT Register. Data is clocked in LSB(D0) first.

The shift register must be loaded while LE is kept LOW to prevent changing the attenuation value during data is inputted.

**Figure 5. Serial Register Map**



The serial register consist of 16 bits as shown in Figure 5. First 8 bits from LSB are Attenuation word, 8 bits after that are Address word. The Attenuation word is DSA attenuation control bit and the Address word is static logical bit determined by A0, A1 and A2 digital inputs. The attenuation word is derived directly from the value of the attenuation state. To find the attenuation word, multiply the value of the state by four because of 0.25dB step up to 31.75dB ( total 127 Attenuation state), then convert to binary.

For example, to program attenuation 15.75dB state of Addr[5] BDA4730 :

|                   |                                       |
|-------------------|---------------------------------------|
| Attenuation State | Address state                         |
| 4 x 15.75 = 63    | Digital input of A2, A1, A0 pin = 101 |
| 63 -> 00111111    | A7 - A0 : xxxxx101                    |

Serial Input : xxxxx10100111111

|    |    |    |    |    |    |    |    |    |    |    |    |    |    |    |    |   |
|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|---|
| x  | x  | x  | x  | x  | x  | 1  | 0  | 1  | 0  | 0  | 1  | 1  | 1  | 1  | 1  | 1 |
| A7 | A6 | A5 | A4 | A3 | A2 | A1 | A0 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |   |

**Table 9. Truth Table for Address Control Word**

| Address Digital Control Input |    |    |    |    |      |      |          | Address Setting | Addr No. |
|-------------------------------|----|----|----|----|------|------|----------|-----------------|----------|
| A7 (MSB)                      | A6 | A5 | A4 | A3 | A2   | A1   | A0 (LSB) |                 |          |
| X                             | X  | X  | X  | X  | LOW  | LOW  | LOW      | 000             | Addr[0]  |
| X                             | X  | X  | X  | X  | LOW  | LOW  | HIGH     | 001             | Addr[1]  |
| X                             | X  | X  | X  | X  | LOW  | HIGH | LOW      | 010             | Addr[2]  |
| X                             | X  | X  | X  | X  | LOW  | HIGH | HIGH     | 011             | Addr[3]  |
| X                             | X  | X  | X  | X  | HIGH | LOW  | LOW      | 100             | Addr[4]  |
| X                             | X  | X  | X  | X  | HIGH | LOW  | HIGH     | 101             | Addr[5]  |
| X                             | X  | X  | X  | X  | HIGH | HIGH | LOW      | 110             | Addr[6]  |
| X                             | X  | X  | X  | X  | HIGH | HIGH | HIGH     | 111             | Addr[7]  |

**Table 10. Mode Selection**

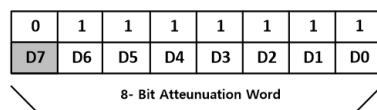
| P/S  | Control Mode       |
|------|--------------------|
| LOW  | Parallel           |
| HIGH | Serial Addressable |

### Power-UP states Settings

The BDA4730 will always initialize to the maximum attenuation setting (31.75 dB) on power-up for both the Serial and Latched Parallel modes of operation and will remain in this setting until the user latches in the next programming word.

In Direct Parallel mode, the DSA can be preset to any state within the 31.75 dB range by pre-setting the Parallel control pins prior to power-up. In this mode, there is a 400 μs delay between the time the DSA is powered-up to the time the desired state is set.

**Figure 6. Default Attenuation Word for Power-up state**



### Programming Options

#### Parallel Control Mode

The parallel control interface has seven digital control input lines (D6 to D0) to set the attenuation value. D6 is the most significant bit (MSB) that selects the 16 dB attenuator stage, and D0 is the least significant bit (LSB) that selects the 0.25 dB attenuator stage (see Figure 7).

#### Direct Parallel Mode

For direct parallel mode, The LE pin must be kept HIGH. The attenuation state is changed by the control voltage inputs (D0 to D6) directly. This mode is ideal for manual control of the attenuator. In this mode the device will immediately react to any voltage changes to the parallel control pins [pins 26, 27, 28, 29, 30, 31, 32]. Use direct parallel mode for the fastest settling time.

#### Latched Parallel Mode

The LE pin must be kept LOW when changing the control voltage inputs (D0 to D6) to set the attenuation state. When the desired state is set, LE must be toggled HIGH to transfer the 7-bit data to the bypass switches of the attenuator array, and then toggled LOW to latch the change into the device until the next desired attenuation change (see Figure 7 and Table 11).

- Set P/S is logic LOW.
- Set LE to logic LOW.
- Adjust pins [26, 27, 28, 29, 30, 31, 32] to the desired attenuation setting. (Note the device will not react to these pins while LE is a logic LOW).
- Pull LE to a logic HIGH. The device will then transition to the attenuation settings reflected by pins D6 - D0.
- If LE is pulled to a logic LOW then the attenuator will not change state.

Latched Parallel Mode implies a default state for when the device is first powered up with P/S pin set for logic LOW and LE logic LOW. In this case the default setting is **Maximum attenuation**.

### Switching Feature Description

#### Glitch-Safe Attenuation State Transient

The BDA4730 is the latest product applied *Glitch-Safe* technology with less than 1dB ringing (pos/neg) across the attenuation range when changing attenuation states. This technology protects Amplifiers or ADC during transitions between attenuation states. (see Figure 40,41).

Table 11. Truth Table for the Parallel Control Word

| D6   | D5   | D4   | D3   | D2   | D1   | D0   | P/S | LE   | Attenuation State(dB) |
|------|------|------|------|------|------|------|-----|------|-----------------------|
| LOW  | LOW  | LOW  | LOW  | LOW  | LOW  | LOW  | LOW | HIGH | 0 (RL)                |
| LOW  | LOW  | LOW  | LOW  | LOW  | LOW  | HIGH | LOW | HIGH | 0.25                  |
| LOW  | LOW  | LOW  | LOW  | LOW  | HIGH | LOW  | LOW | HIGH | 0.5                   |
| LOW  | LOW  | LOW  | LOW  | HIGH | LOW  | LOW  | LOW | HIGH | 1.0                   |
| LOW  | LOW  | LOW  | HIGH | LOW  | LOW  | LOW  | LOW | HIGH | 2.0                   |
| LOW  | LOW  | HIGH | LOW  | LOW  | LOW  | LOW  | LOW | HIGH | 4.0                   |
| LOW  | HIGH | LOW  | LOW  | LOW  | LOW  | LOW  | LOW | HIGH | 8.0                   |
| HIGH | LOW  | LOW  | LOW  | LOW  | LOW  | LOW  | LOW | HIGH | 16.0                  |
| HIGH | HIGH | HIGH | HIGH | HIGH | HIGH | HIGH | LOW | HIGH | 31.75                 |

Figure 7. Latched Parallel Mode Timing Diagram

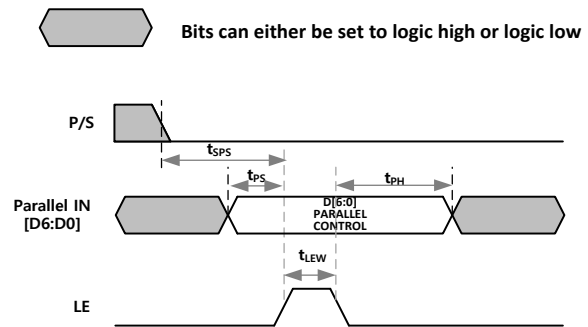


Table 12. Parallel Interface Timing Specifications

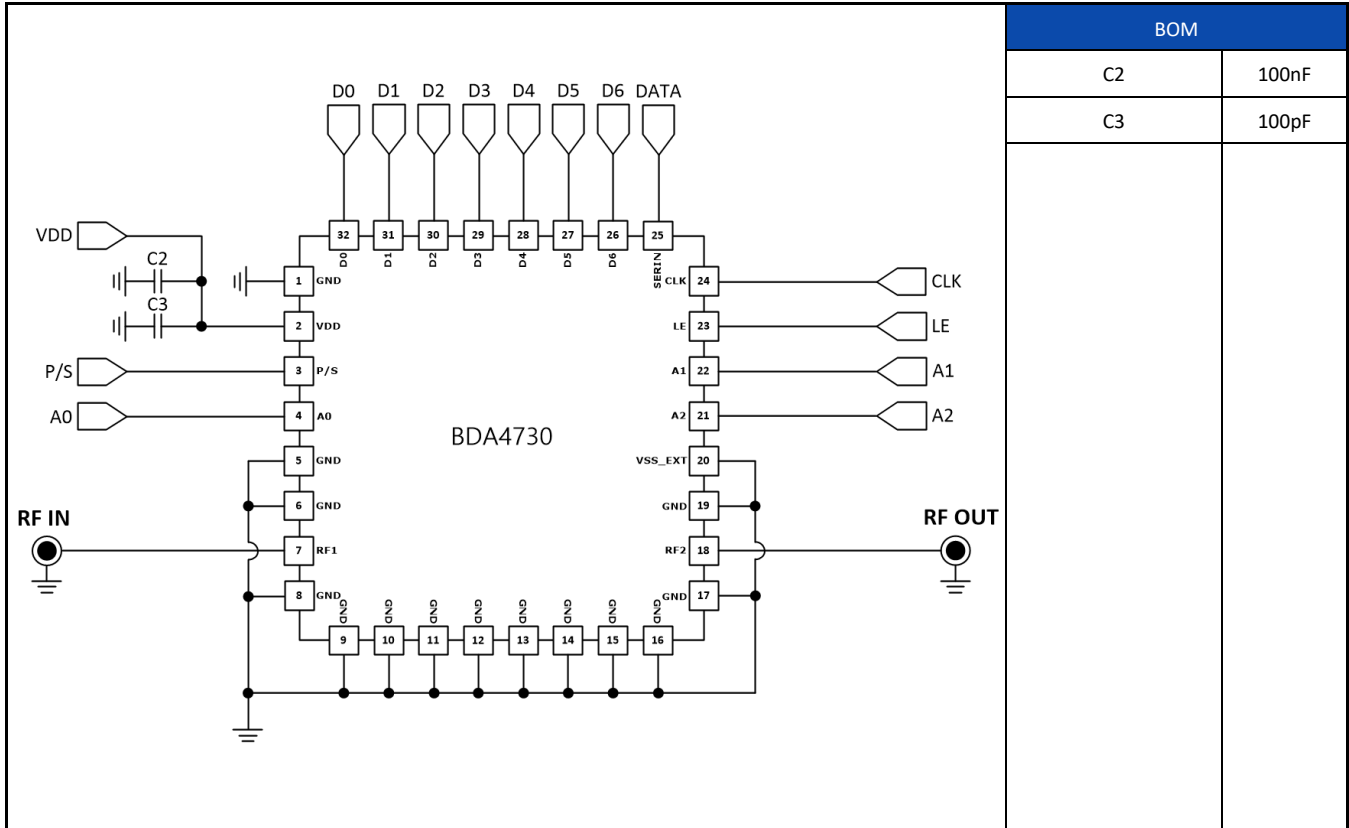
| Symbol    | Parameter                          | Min | Typ | Max | Unit |
|-----------|------------------------------------|-----|-----|-----|------|
| $t_{SPS}$ | Serial to Parallel Mode Setup Time | 100 |     |     | ns   |
| $t_{LEW}$ | Minimum LE pulse width             | 10  |     |     | ns   |
| $t_{PH}$  | Data hold time from LE             | 10  |     |     | ns   |
| $t_{PS}$  | Data setup time to LE              | 10  |     |     | ns   |



### Typical RF Performance Plot - BDA4730 EVK - PCB ( Typical Application Circuits )

Typical Performance Data @ 25°C and  $V_{DD} = 3.3V$ , EVKit RF connector and board losses are de-embedded, unless otherwise noted

Table 13. Typical Application Circuits



1. See the page 21 the Evaluation Board Circuits for the detailed application circuit information.

Figure 8. Insertion Loss vs Temp.

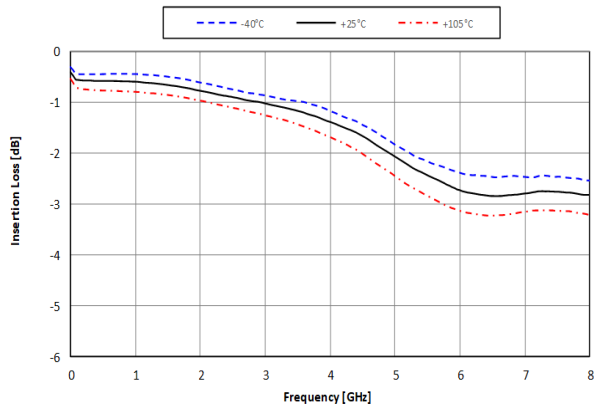
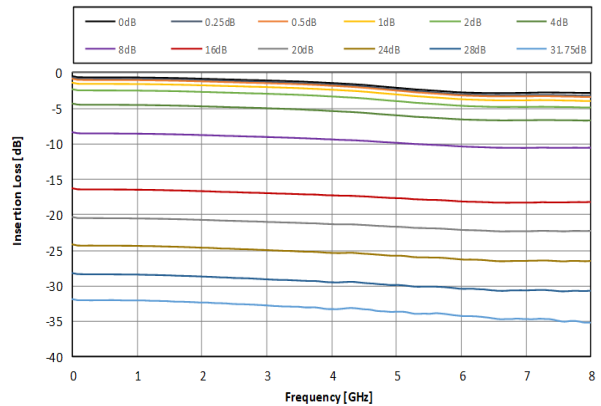


Figure 9. Insertion Loss vs ATT Setting



### Typical RF Performance Plot - BDA4730 EVK - PCB ( Typical Application Circuits )

Typical Performance Data @ 25°C and  $V_{DD} = 3.3V$ , EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 10. Input Return Loss vs ATT Setting

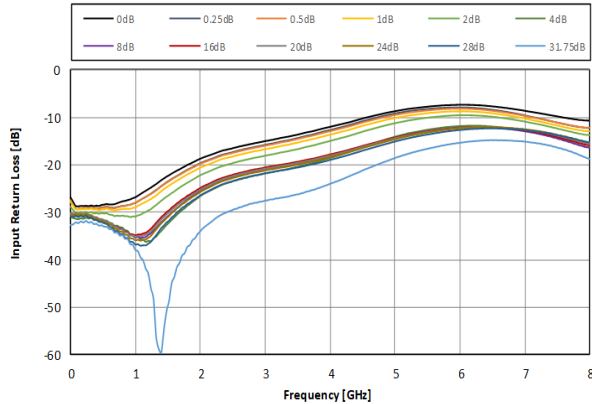


Figure 11. Output Return Loss vs ATT Setting

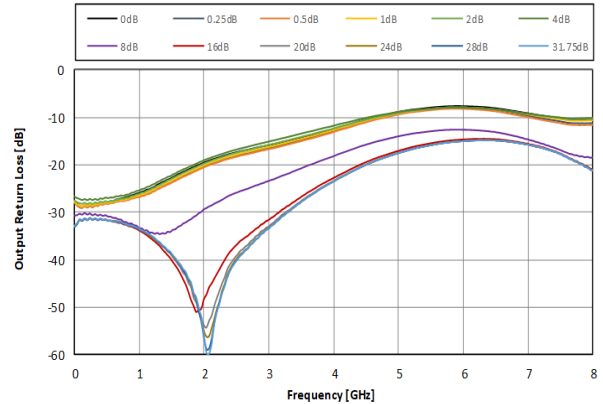


Figure 12. Input Return Loss vs Temp. @ ATT = 16dB

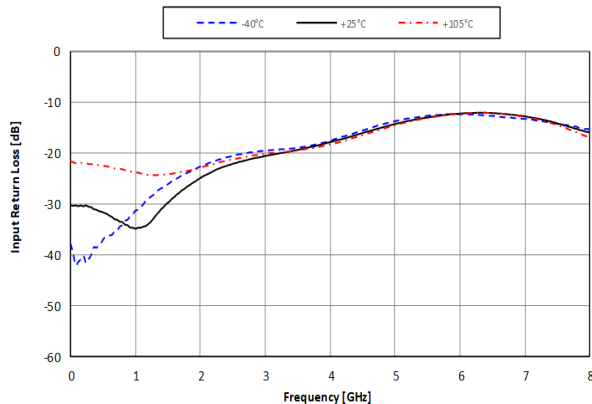


Figure 13. Output Return Loss vs Temp. @ ATT = 16dB

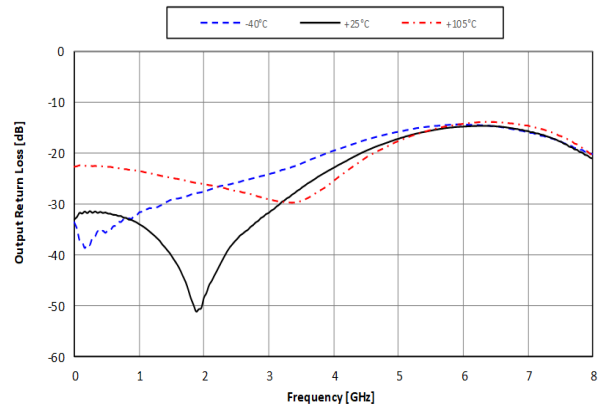


Figure 14. Relative Phase Error vs ATT Setting

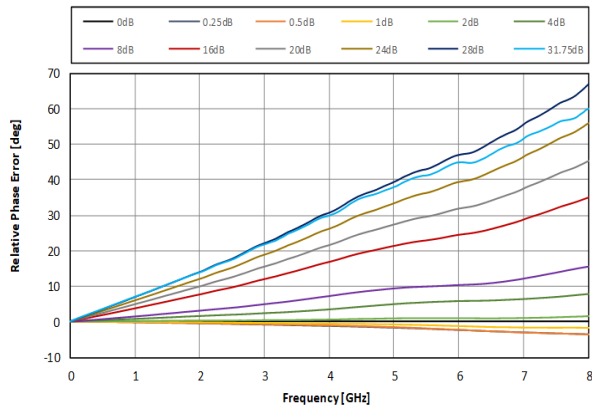
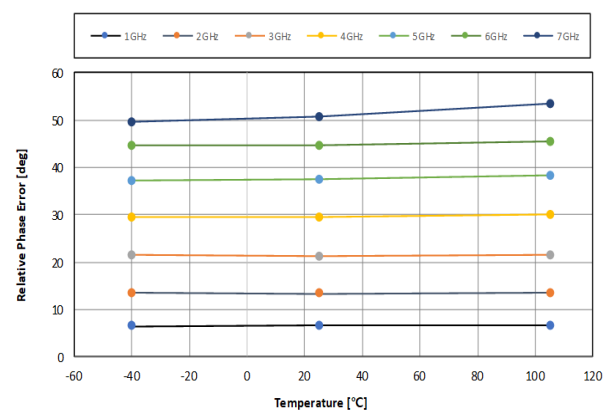
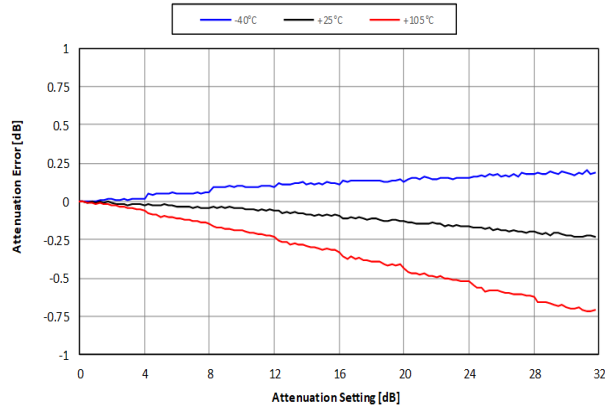
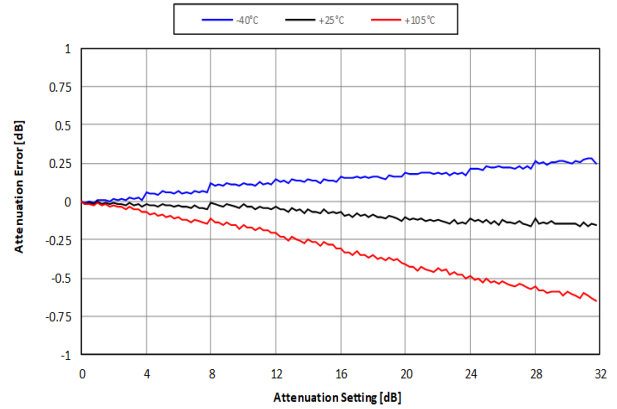
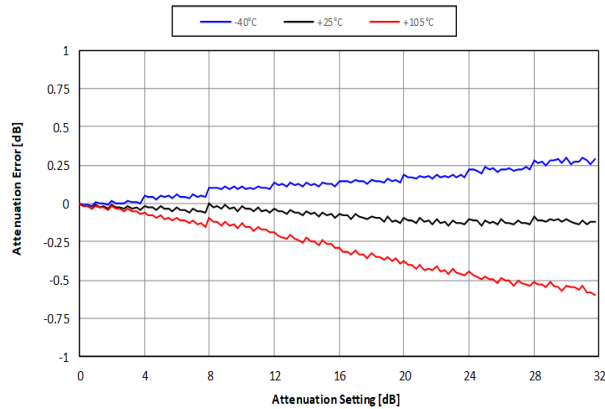
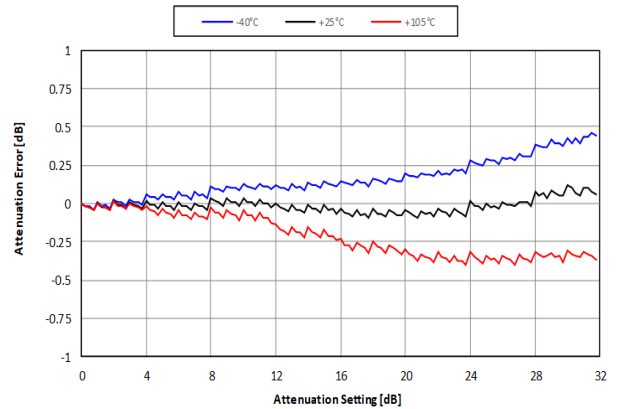
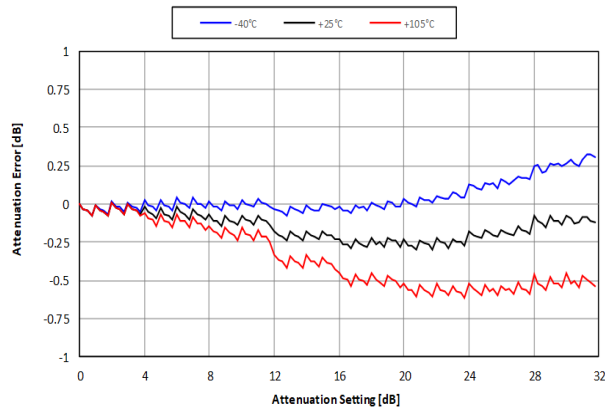
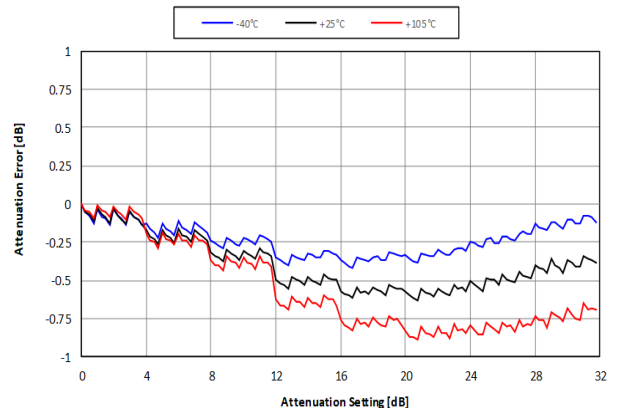


Figure 15. Relative Phase Error vs Frequency @ ATT = 31.5dB



**Typical RF Performance Plot - BDA4730 EVK - PCB ( Typical Application Circuits )**

 Typical Performance Data @ 25°C and  $V_{DD} = 3.3V$ , EVKit RF connector and board losses are de-embedded, unless otherwise noted

**Figure 16. ATT Error vs Temp. @ 900MHz**

**Figure 17. ATT Error vs Temp. @ 1800MHz**

**Figure 18. ATT Error vs Temp. @ 2200MHz**

**Figure 19. ATT Error vs Temp. @ 3500MHz**

**Figure 20. ATT Error vs Temp. @ 4600MHz**

**Figure 21. ATT Error vs Temp. @ 5800MHz**


### Typical RF Performance Plot - BDA4730 EVK - PCB ( Typical Application Circuits )

Typical Performance Data @ 25°C and  $V_{DD} = 3.3V$ , EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 22. IIP3 vs Temp. @ 2500MHz

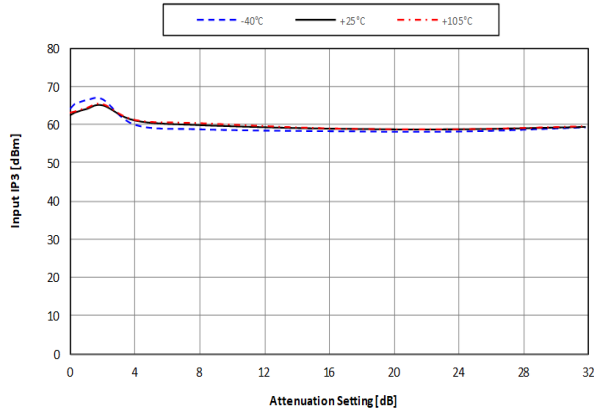


Figure 23. IIP3 vs Temp. @ 3500MHz

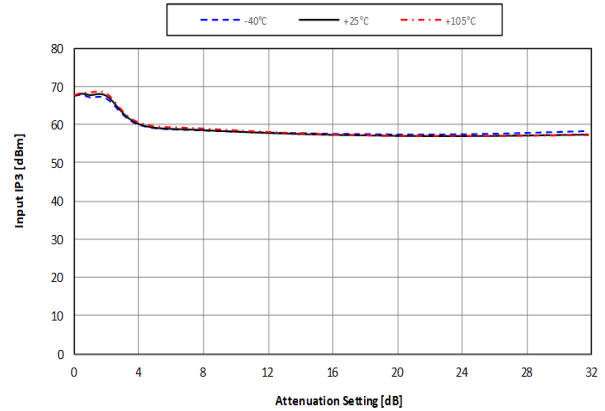


Figure 24. IIP3 vs Temp. @ 4500MHz

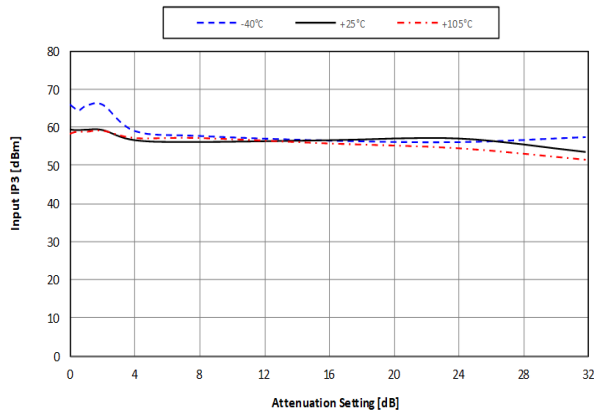


Figure 25. IIP3 vs Temp. @ 6400MHz

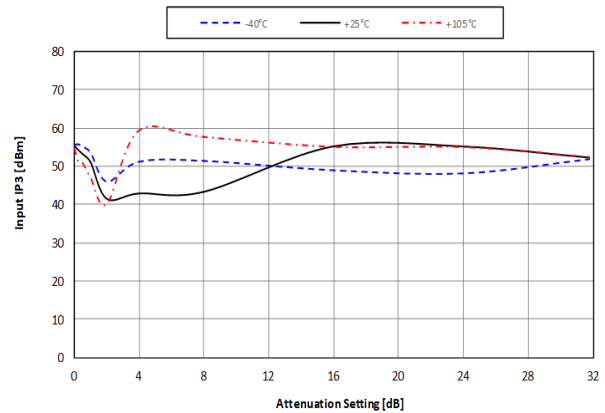


Figure 26. IIP3 vs Temp. @ 7250MHz

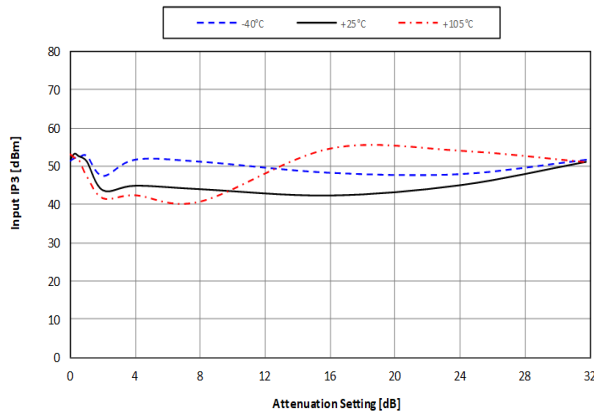
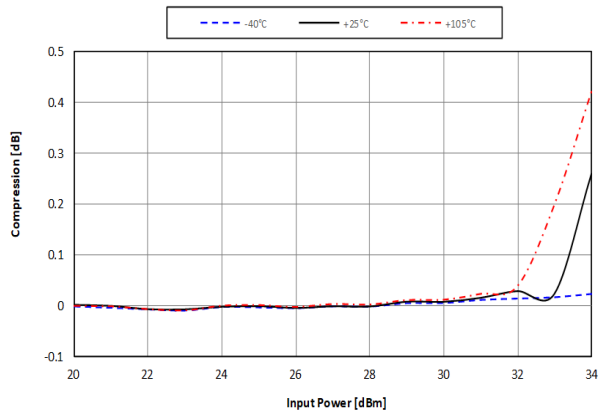


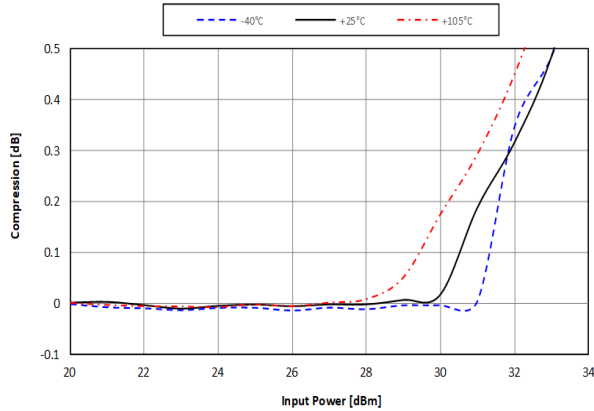
Figure 27. Input 0.1dB Compression vs Temp. @ 2500MHz



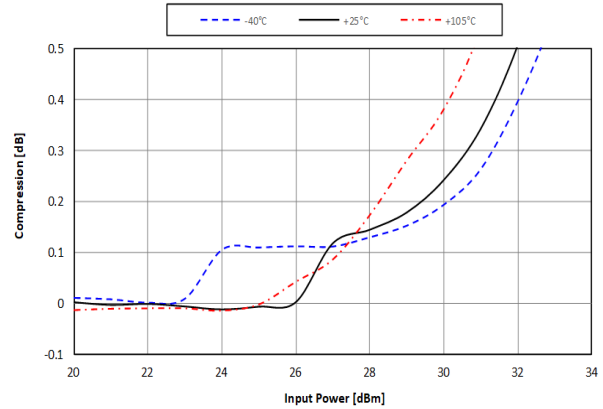
### Typical RF Performance Plot - BDA4730 EVK - PCB ( Typical Application Circuits )

Typical Performance Data @ 25°C and  $V_{DD} = 3.3V$ , EVKit RF connector and board losses are de-embedded, unless otherwise noted

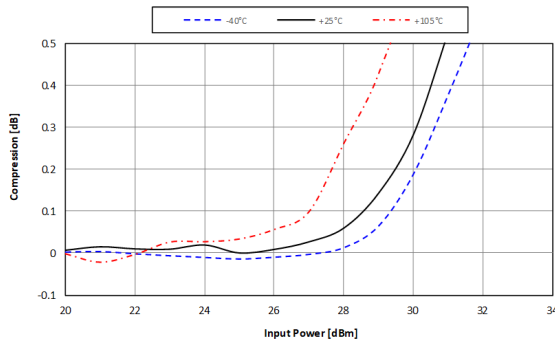
**Figure 28. Input 0.1dB Compression vs Temp. @ 3500MHz**



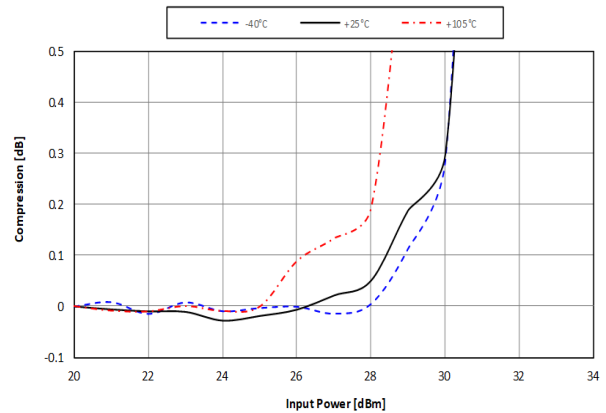
**Figure 29. Input 0.1dB Compression vs Temp. @ 4500MHz**



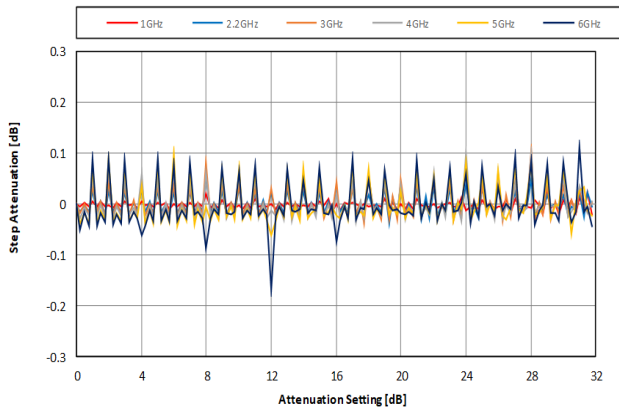
**Figure 30. Input 0.1dB Compression vs Temp. @ 5500MHz**



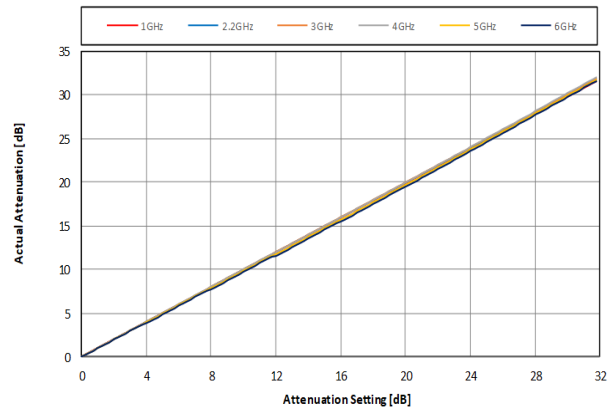
**Figure 31. Input 0.1dB Compression vs Temp. @ 7250MHz**



**Figure 32. 0.25dB Step ATT vs Frequency**

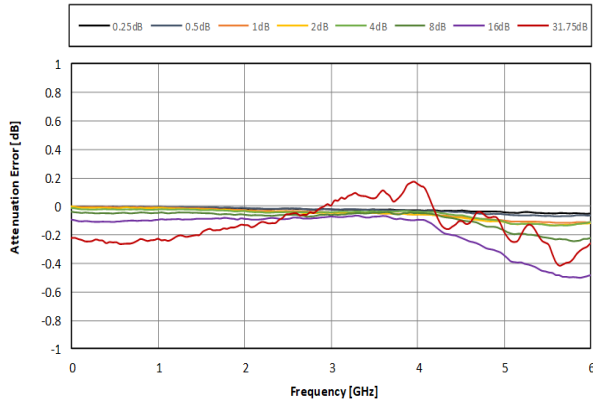
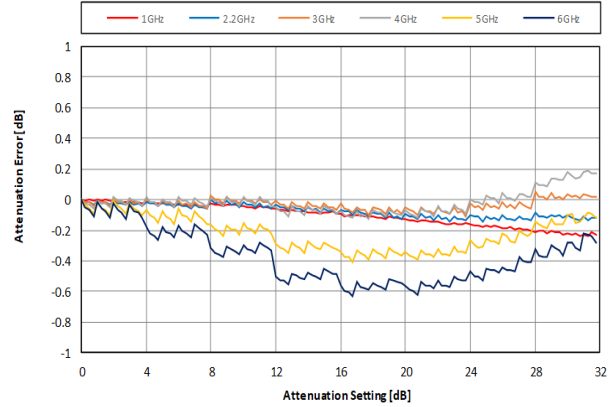
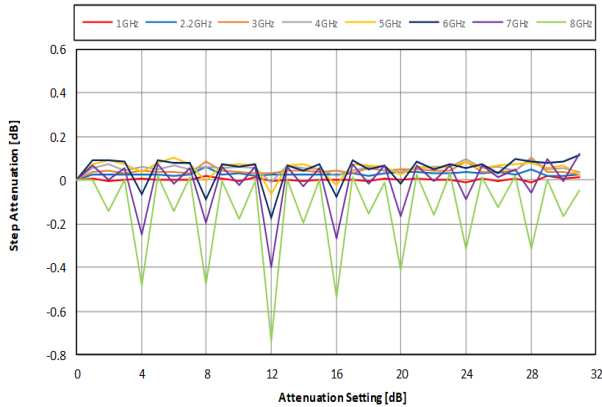
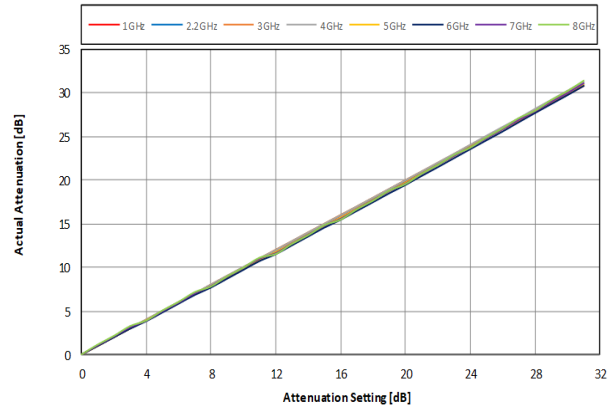
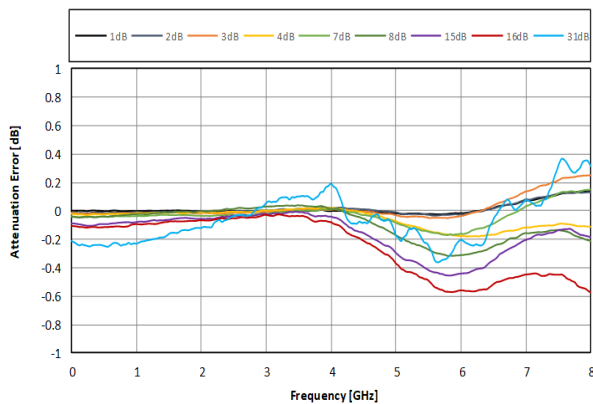
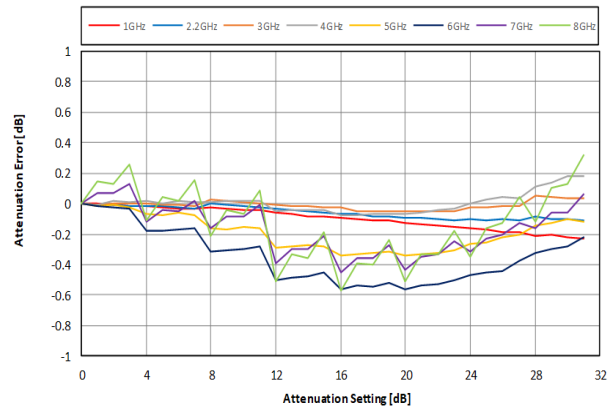


**Figure 33. 0.25dB Step Actual ATT vs Frequency**



**Typical RF Performance Plot - BDA4730 EVK - PCB ( Typical Application Circuits )**

 Typical Performance Data @ 25°C and  $V_{DD} = 3.3V$ , EVKit RF connector and board losses are de-embedded, unless otherwise noted

**Figure 34. 0.25dB Major State Bit Error vs ATT Setting**

**Figure 35. 0.25dB Step ATT Error vs Frequency**

**Figure 36. 1dB Step ATT vs Frequency**

**Figure 37. 1dB Step Actual ATT vs Frequency**

**Figure 38. 1dB Major State Bit Error vs ATT Setting**

**Figure 39. 1dB Major ATT Error vs Frequency**


### Typical RF Performance Plot - BDA4730 EVK - PCB ( Typical Application Circuits )

Typical Performance Data @ 25°C and  $V_{DD} = 3.3V$ , EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 40. ATT Transient (15.75 to 16dB, Pin=18dBm)

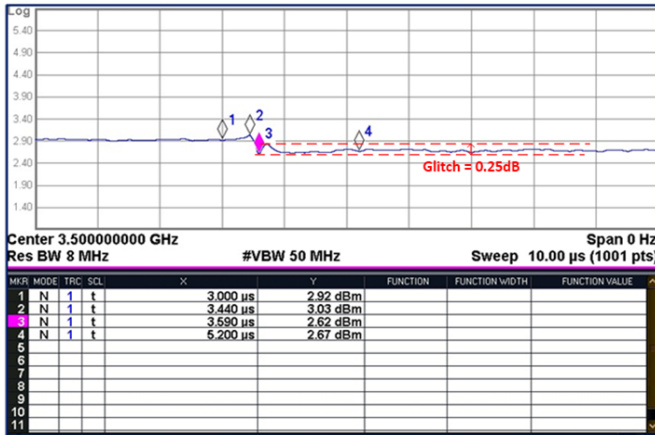
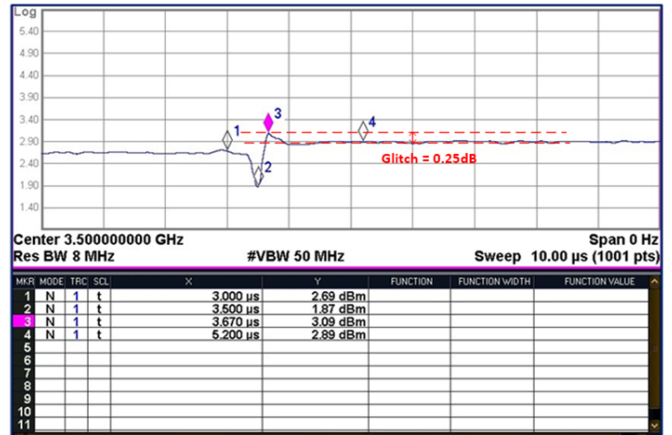


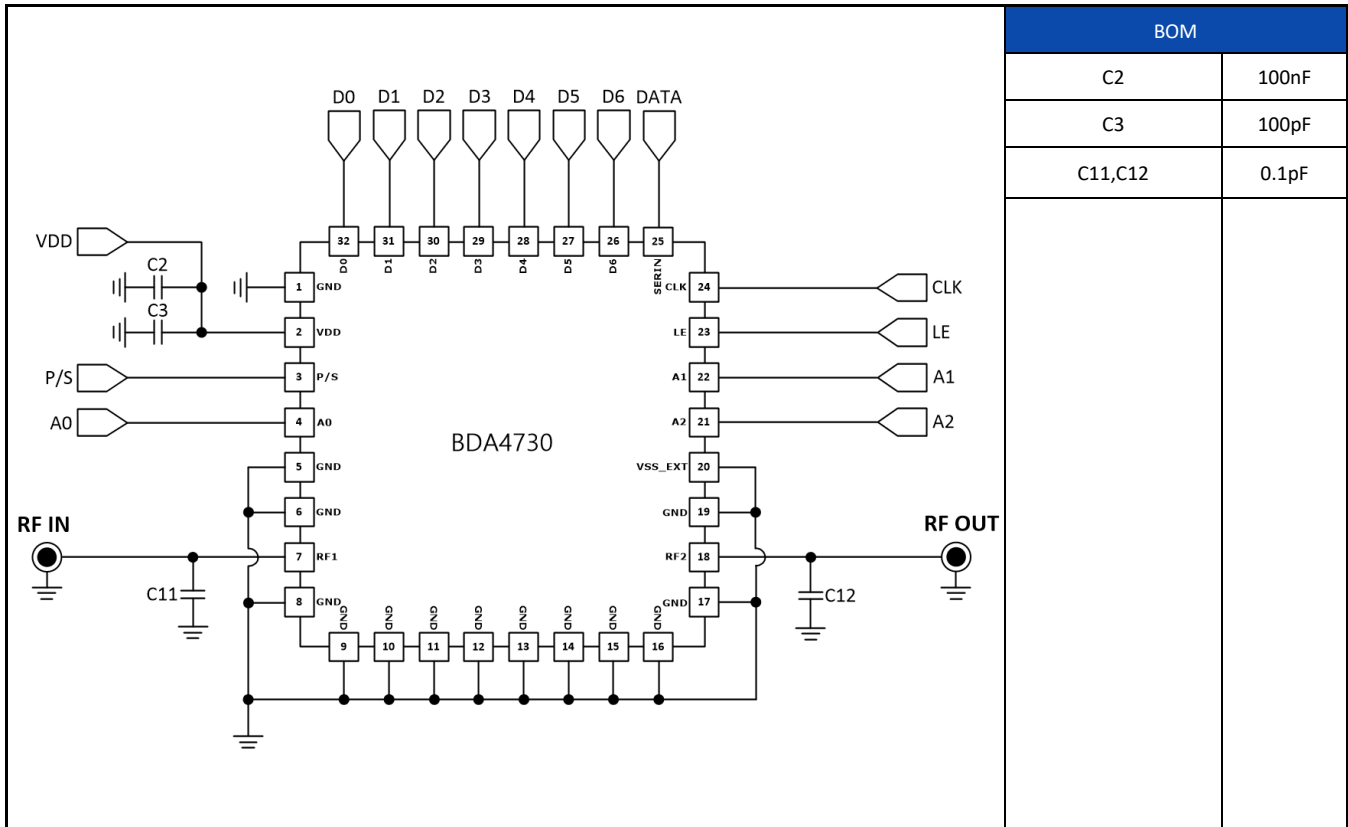
Figure 41. ATT Transient (16 to 15.75dB, Pin=18dBm)



### Typical RF Performance Plot - BDA4730 EVK - PCB ( Optimized Return Loss Application Circuits )

Typical Performance Data @ 25°C and  $V_{DD} = 3.3V$ , EVKit RF connector and board losses are de-embedded, unless otherwise noted

Table 14. Optimized Return Loss Application Circuits for 4GHz - 8.5GHz



1. See the page 21 the Evaluation Board Circuits for the detailed application circuit information.
2. In order to optimized Return loss for above 4GHz, shunt capacitor 0.1pF was added near RF1 & RF2, respectively.

Figure 42. Insertion Loss vs Temp.

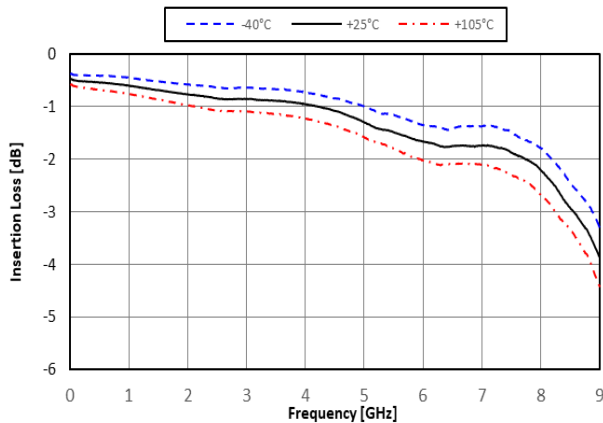
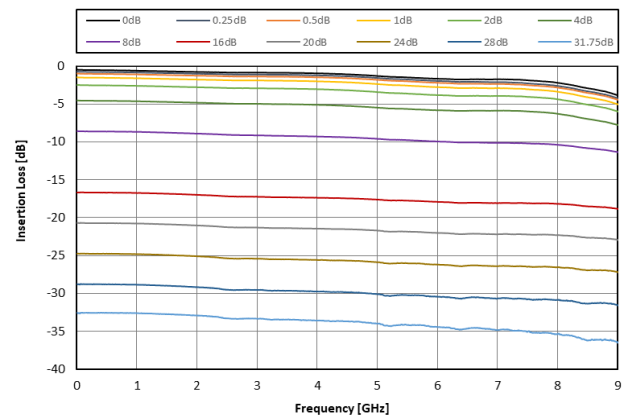


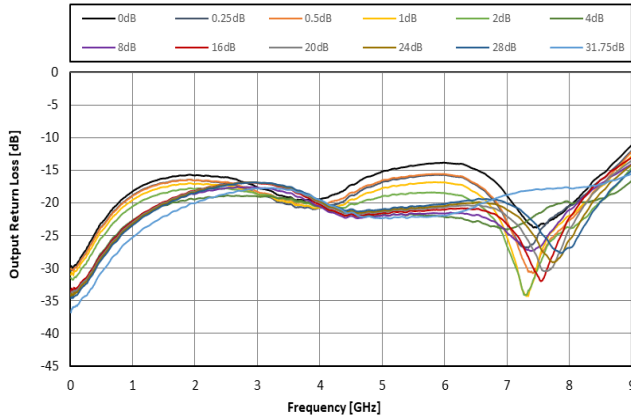
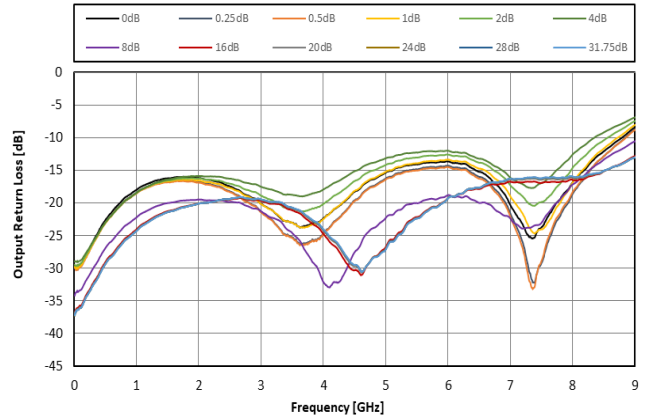
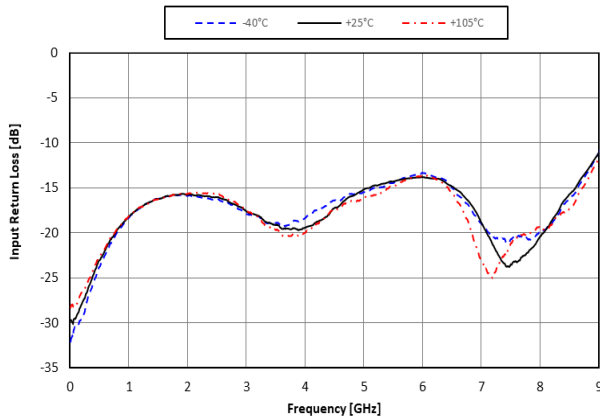
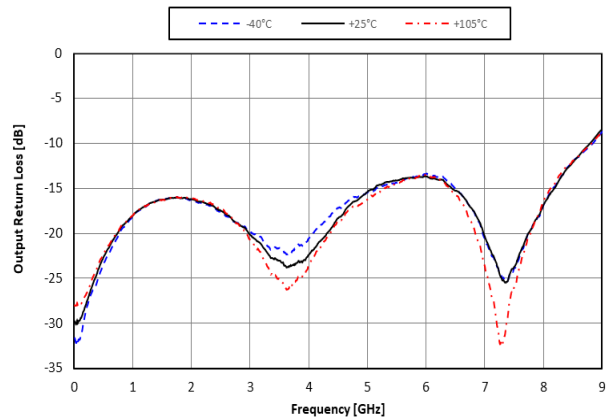
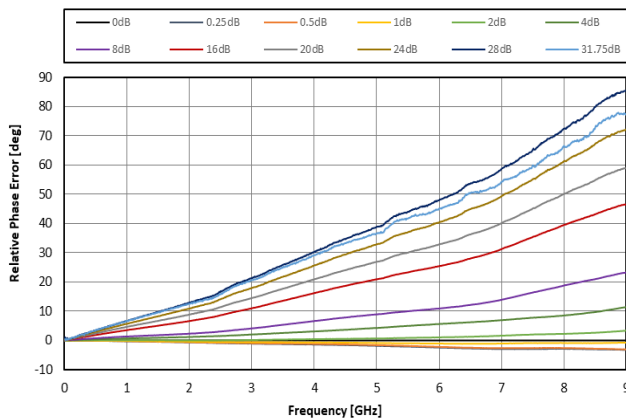
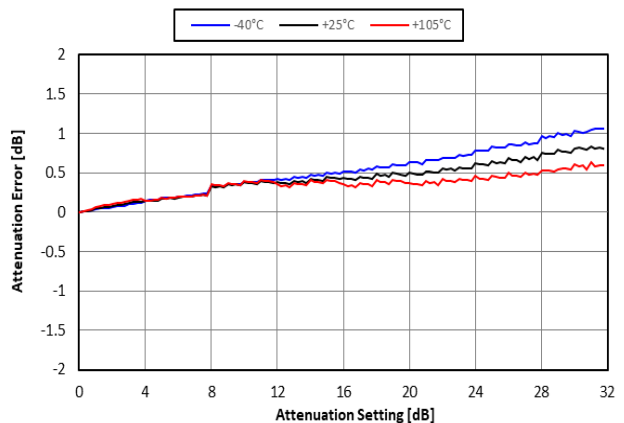
Figure 43. Insertion Loss vs ATT Setting





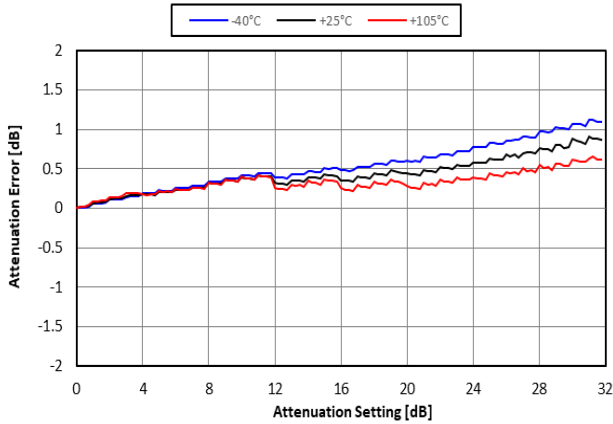
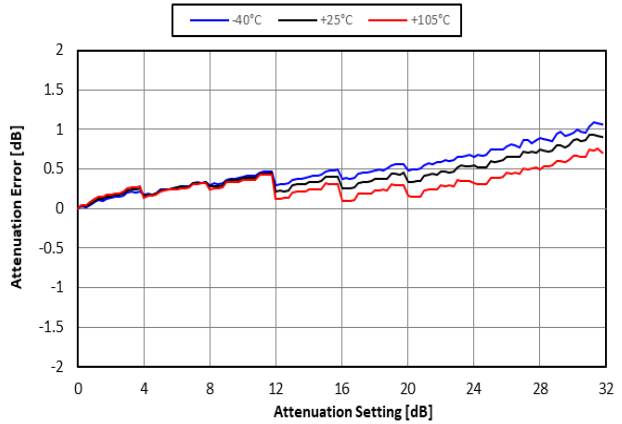
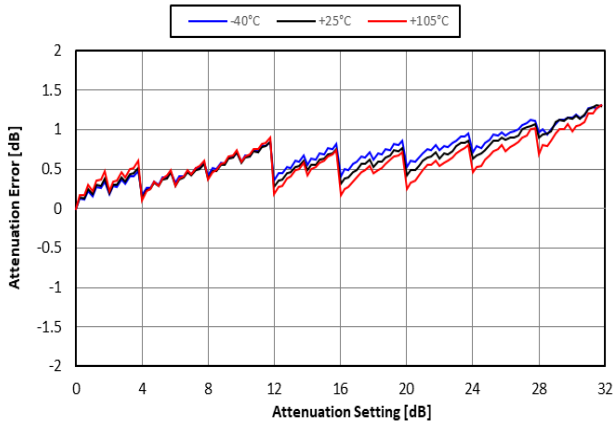
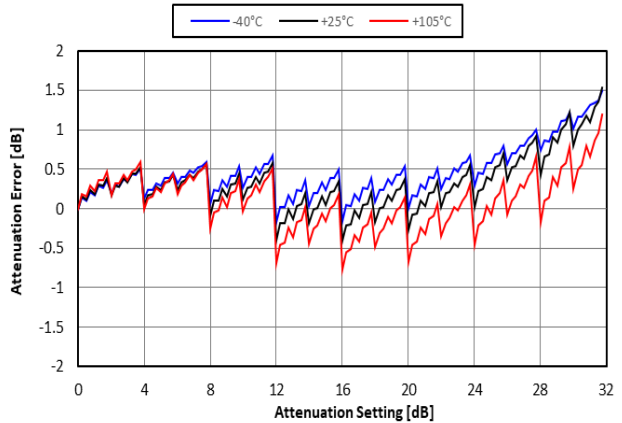
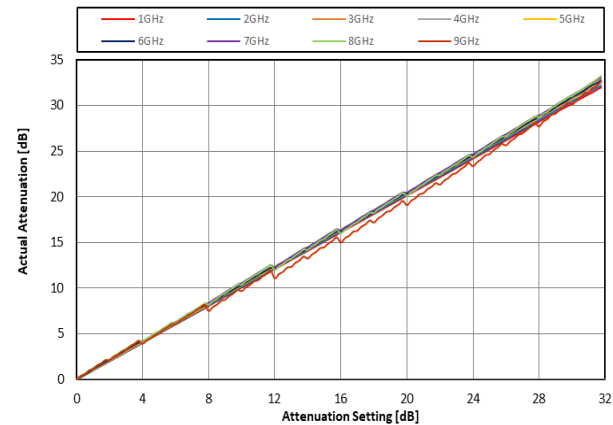
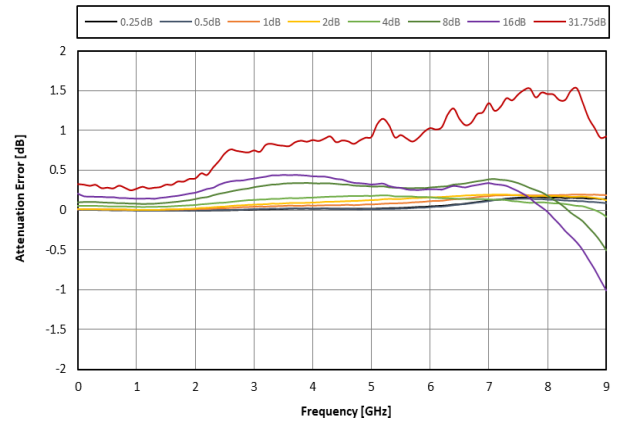
**Typical RF Performance Plot - BDA4730 EVK - PCB ( Optimized Return Loss Application Circuits )**

 Typical Performance Data @ 25°C and  $V_{DD} = 3.3V$ , EVKit RF connector and board losses are de-embedded, unless otherwise noted

**Figure 44. Input Return Loss vs ATT Setting**

**Figure 45. Output Return Loss vs ATT Setting**

**Figure 46. Input Return Loss vs Temp. @ ATT = 0dB**

**Figure 47. Output Return Loss vs Temp. @ ATT = 0dB**

**Figure 48. Relative Phase Error vs ATT Setting**

**Figure 49. ATT Error vs Temp. @ 3500MHz**


**Typical RF Performance Plot - BDA4730 EVK - PCB ( Optimized Return Loss Application Circuits )**

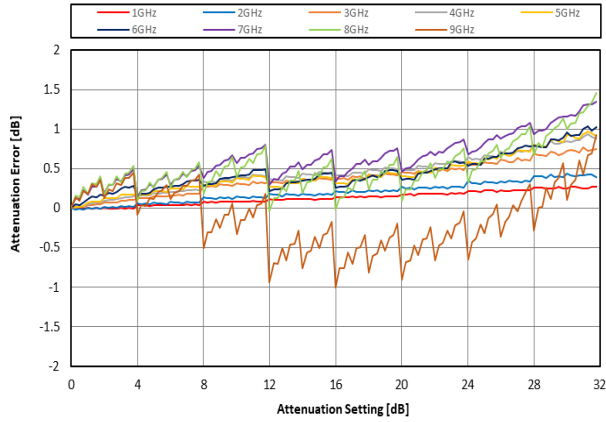
 Typical Performance Data @ 25°C and  $V_{DD} = 3.3V$ , EVKit RF connector and board losses are de-embedded, unless otherwise noted

**Figure 50. ATT Error vs Temp. @ 4600MHz**

**Figure 51. ATT Error vs Temp. @ 5800MHz**

**Figure 52. ATT Error vs Temp. @ 7200MHz**

**Figure 53. ATT Error vs Temp. @ 8500MHz**

**Figure 54. 0.25dB Step Actual ATT vs Frequency**

**Figure 55. 0.25dB Major State Bit Error vs ATT Setting**


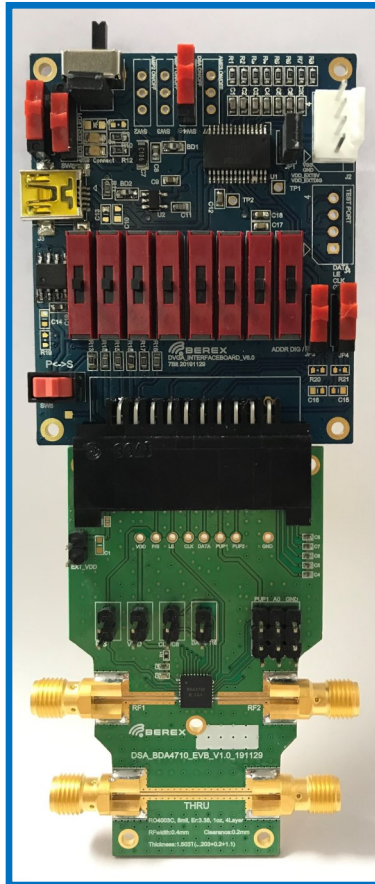
**Typical RF Performance Plot - BDA4730 EVK - PCB ( Optimized Return Loss Application Circuits )**

Typical Performance Data @ 25°C and  $V_{DD} = 3.3V$ , EVKit RF connector and board losses are de-embedded, unless otherwise noted

**Figure 56. 0.25dB Step ATT Error vs Frequency**



### BDA4730 Evaluation board Kit Description



**Figure 57. BDA4730 EVK**

#### Evaluation board Kit Introduction

BDA4730 Evaluation Kit is made up of a combination of an RF board and an interface board

The schematic of the BDA4730 evaluation RF board is shown in Figure 57. The BDA4730 evaluation RF board is constructed of a 4-layer material with a copper thickness of 1oz(0.035mm) on each layer. Every copper layer is separated with a dielectric material. The top dielectric material is 8 mils RO4003. The middle and bottom dielectric materials are FR-4, used for mechanical strength and overall board thickness of approximately 1.63mm.

BDA4730 Evaluation INTERFACE board is assembled with a SP3T switches(D0~D6,LE), SP2T mechanical switch (P/S), and several header & switch.

#### Evaluation Board Programming Using USB Interface

In order to evaluate the BDA4730 performance, the Application Software has to be installed on your computer. And The DSA application software GUI supports Latched Parallel and Serial modes. software can be downloaded from BeRex's website

#### Serial Control Mode

- Set the Address Jumper (A0, A1, A2) to HIGH or LOW (Refer to Address Table 9)
- Connect directly the Evaluation INTERFACE board USB port(J3) to PC
- Set the direction of P<->S Switch to S direction (P/S Logic HIGH)
- Set the D0~D6,LE switch to the middle position.
- Operate the 0~31.75dB attenuation state in GUI and then control the DSA

#### Latched Parallel Control Mode

- Connect directly the Evaluation INTERFACE board USB port(J3) to PC
- Set the direction of P<->S Switch to P direction (P/S Logic LOW)
- Set the D0~D6, LE switch to the middle position.
- Operate the 0~31.75dB attenuation state in GUI and then control the DSA

#### Direct Parallel Control Mode

- Set the direction of P<->S Switch to P direction (P/S Logic LOW)
- Set LE switch to the LOW Position
- For the setting to attenuation state, D0~D6 switches can be combined in manually program, refer to Table 11.

Please refer to user manual for more detailed operation method of BDA4730 EVK.

### BDA4730 Evaluation board Kit Description

Figure 58. Evaluation Board Kit Schematic Diagram

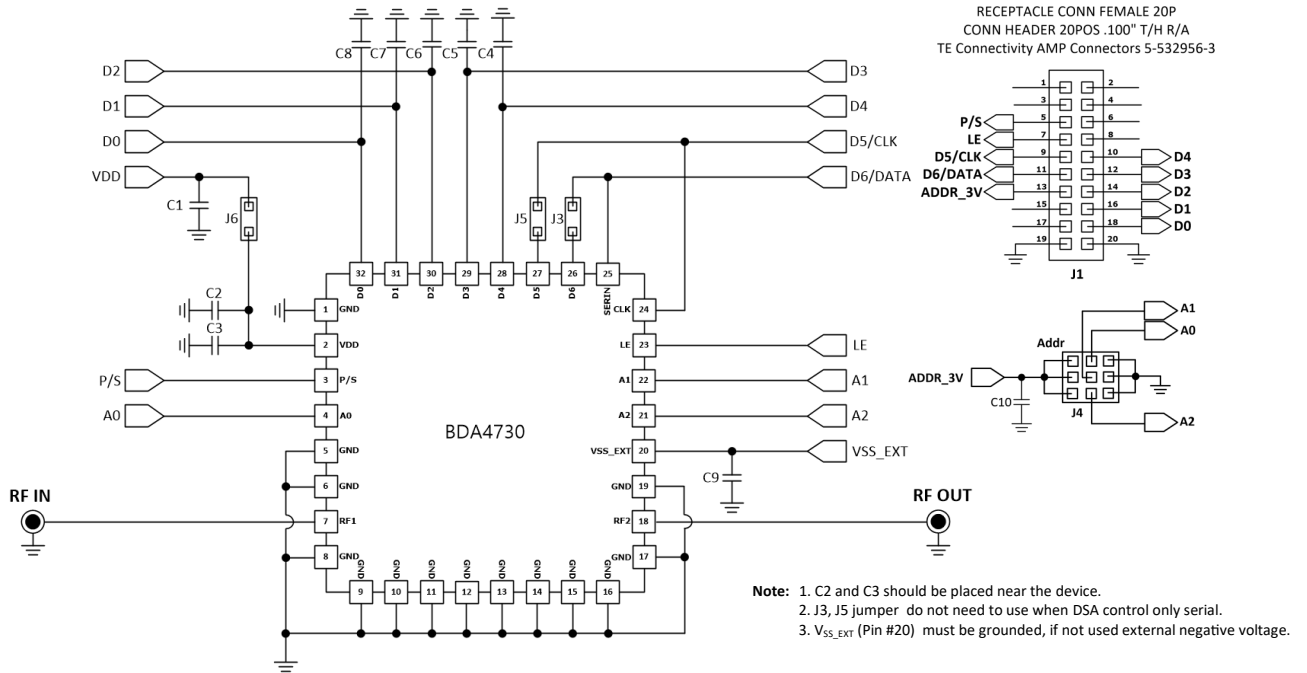


Figure 59. Evaluation Board PCB Layout Information

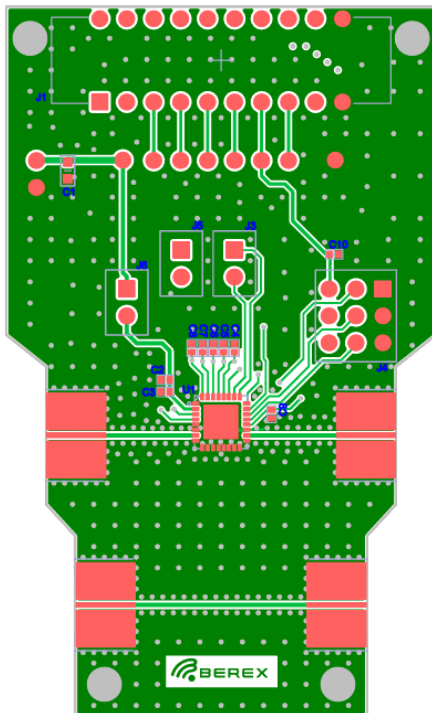


Table 15. Bill of Material - Evaluation Board

| No. | Ref Des     | Part Qty | Value | Description                     | Remark |
|-----|-------------|----------|-------|---------------------------------|--------|
| 1   | C3-C8       | 6        | 100pF | CAP, 0402, CHIP Ceramic, ±0.25% |        |
| 2   | C2,C10      | 2        | 100nF | CAP, 0402, CHIP Ceramic, ±0.25% |        |
| 3   | C9          | 1        | 0 ohm | RES, 0402, CHIP, ±5%            |        |
| 4   | U1          | 1        | Chip  | DSA, BDA4730 QFN5x5 32L         |        |
| 5   | SMA1, SMA2  | 2        | CON   | SMA END LAUNCH                  |        |
| 6   | J1          | 1        | CON   | Receptacle connector 20pin      |        |
| 7   | J2,J3,J5,J6 | 4        | CON   | Header 2.54mm 2pin              |        |
| 8   | J4          | 1        | CON   | Header array 2.54mm 3pin x 3    |        |
| 9   | C1          | 1        | NC    | Not Connected                   |        |

Figure 60. Evaluation Board PCB Layer Information

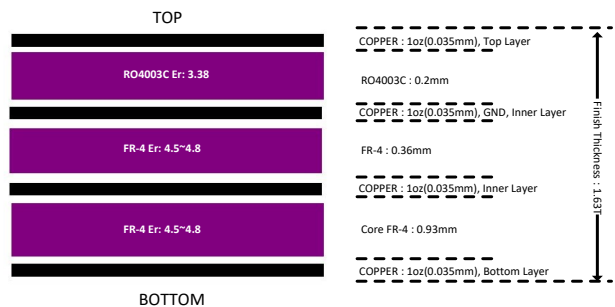
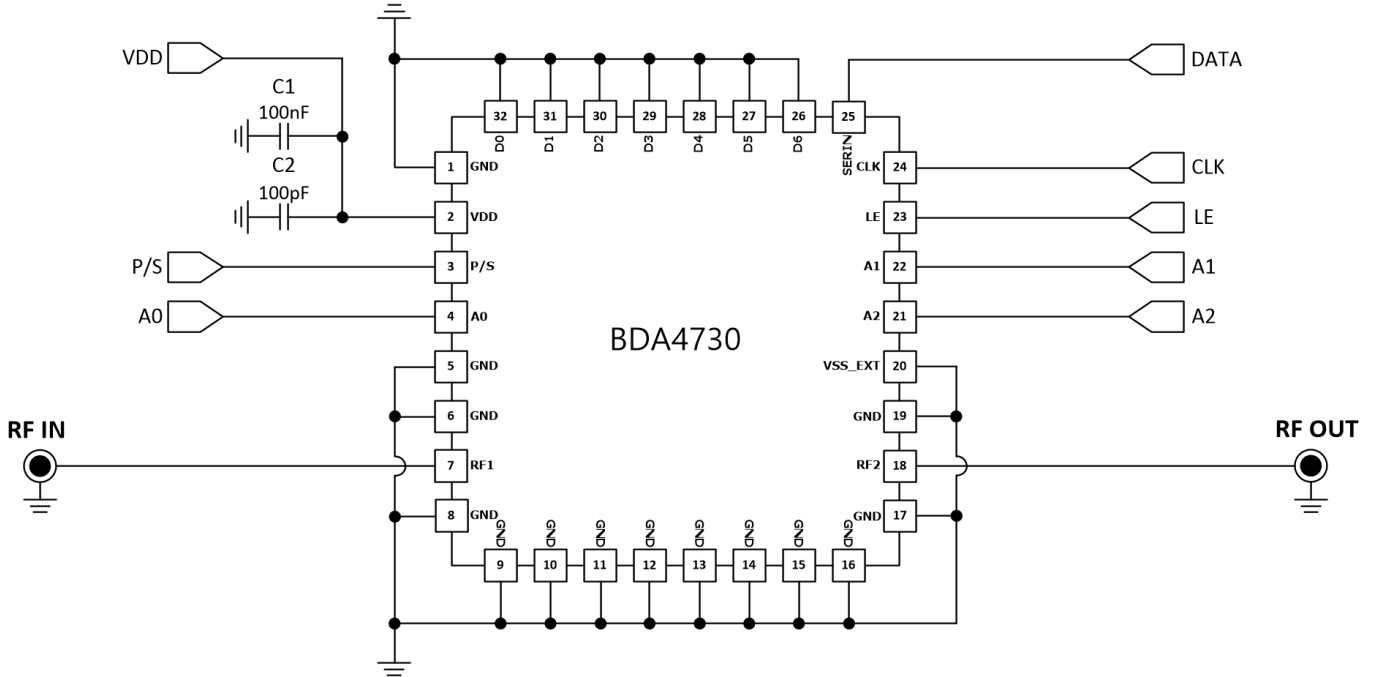


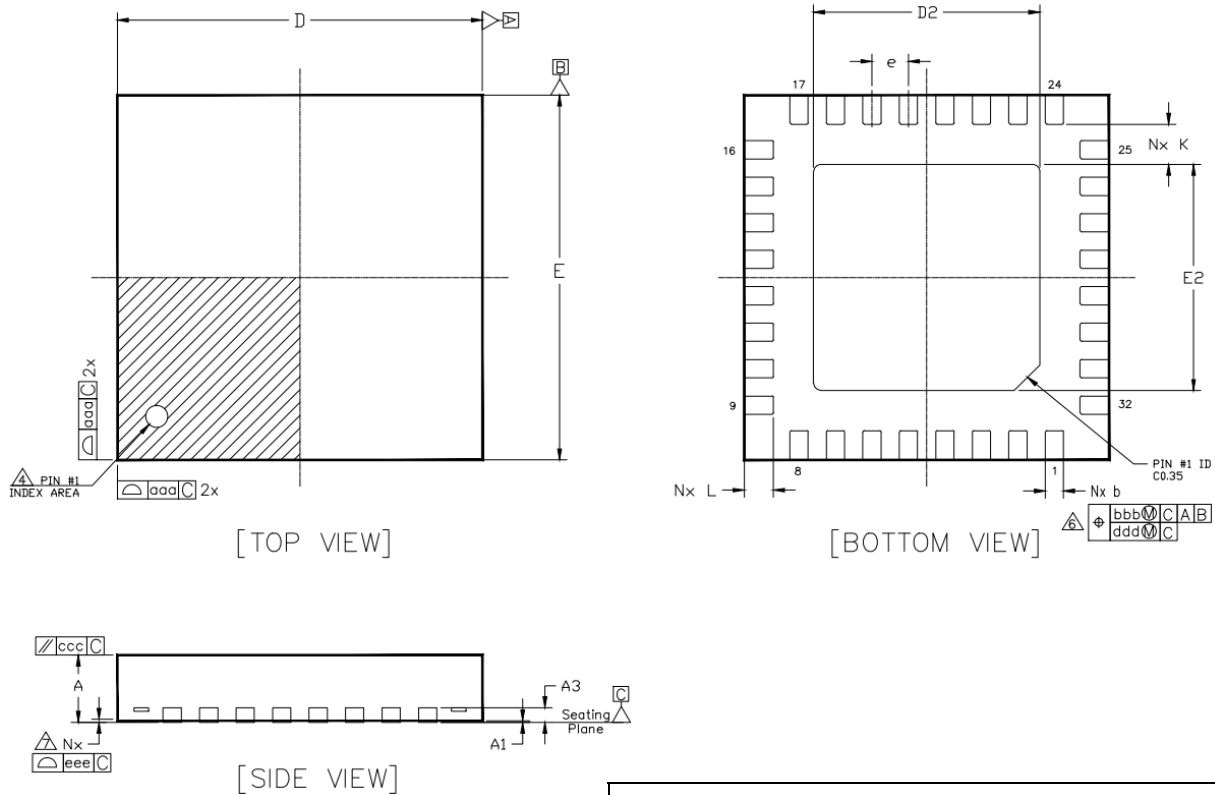
Figure 61. Recommended Serial mode Application Schematic



**Note:** 1. C1 and C2 should be placed near the device.

2. Addressable Pin A0,A1,A2 can be set according to the specified address. If the specified address is 000, all addressable pin(A0,A1,A2) should be grounded.

Figure 62. Packing Outline Dimension



**NOTE :**

1. Dimensioning and tolerancing conform to ASME Y14.5-2009.
2. All dimensions are in millimeters.
3. N is the total number of terminals.
4. The location of the marked terminal #1 identifier is within the hatched area.
5. ND and NE refer to the number of terminals on each D and E side respectively.
6. Dimension b applies to the metallized terminal and is measured between 0.15mm and 0.30mm from the terminal tip. If the terminal has a radius on the other end of it, dimension b should not be measured in that radius area.
7. Coplanarity applies to the terminals and all other bottom surface metallization

| Dimension Table |           |           |         |      |
|-----------------|-----------|-----------|---------|------|
| Symbol          | Thickness |           |         | NOTE |
|                 | MINIMUM   | NOMINAL   | MAXIMUM |      |
| A               | 0.8       | 0.9       | 1       |      |
| A1              | 0         | 0.02      | 0.05    |      |
| A3              | ---       | 0.203 Ref | ---     |      |
| b               | 0.2       | 0.25      | 0.3     | 6    |
| D               |           | 5.0 BSC   |         |      |
| D2              | 3.05      | 3.10      | 3.15    |      |
| E               |           | 5.0 BSC   |         |      |
| E2              | 3.05      | 3.10      | 3.15    |      |
| e               |           | 0.5 BSC   |         |      |
| K               | 0.2       | ---       | ---     |      |
| L               | 0.3       | 0.4       | 0.5     |      |
| aaa             |           | 0.05      |         |      |
| bbb             |           | 0.1       |         |      |
| ccc             |           | 0.1       |         |      |
| ddd             |           | 0.05      |         |      |
| eee             |           | 0.08      |         |      |
| N               |           | 32        |         | 3    |
| ND              |           | 8         |         | 5    |
| NE              |           | 8         |         | 5    |

Figure 63. Recommend Land Pattern

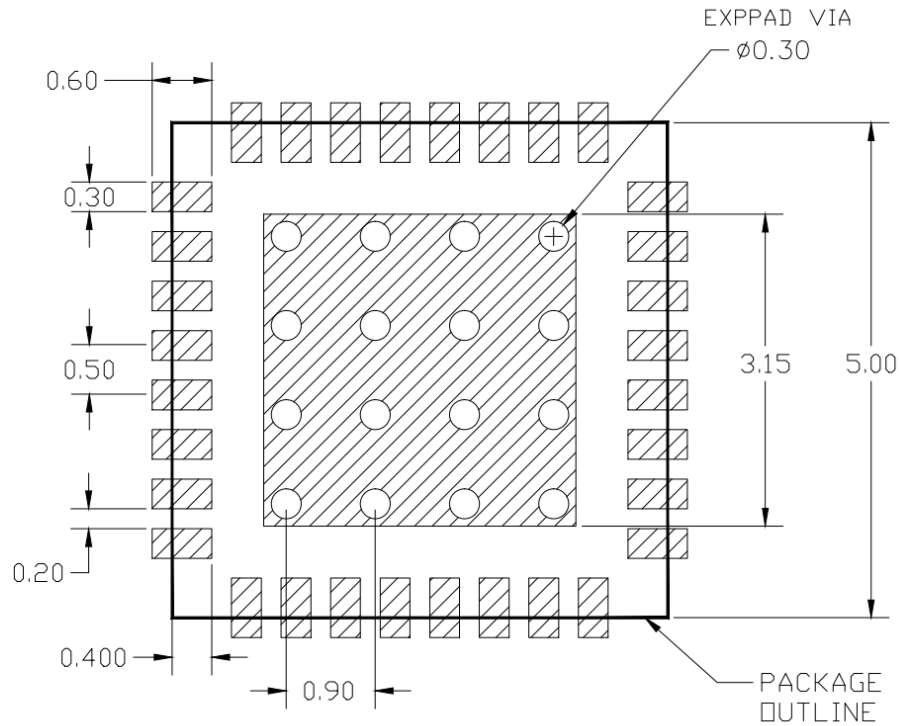


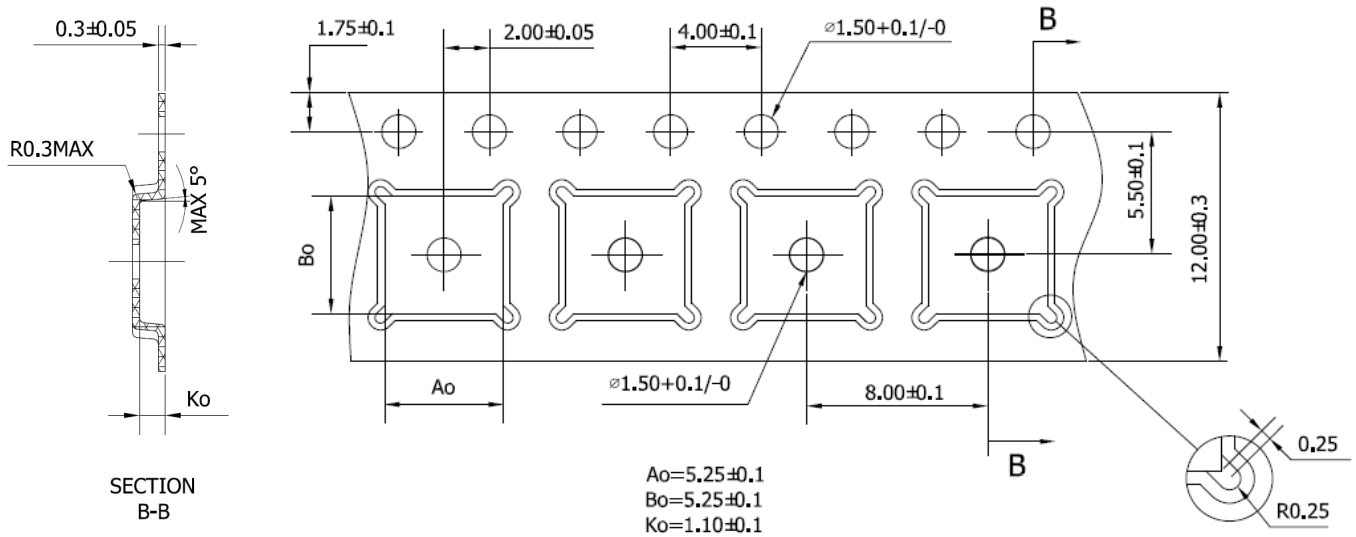
Figure 64. Package Marking



| Marking information: |             |
|----------------------|-------------|
| BDA4730              | Device Name |
| YY                   | Year        |
| WW                   | Work Week   |
| XX                   | LOT Number  |



Figure 65. Tape & Reel



NOTES:

- 1 10 SPROCKET HOLE PITCH CUMULATIVE TOLERANCE  $\pm 0.2$
- 2 CAMBER IN COMPLIANCE WITH EIA 481
- 3 POCKET POSITION RELATIVE TO SPROCKET HOLE MEASURED AS TRUE POSITION OF POCKET, NOT POCKET HOLE

| Packaging information: |       |
|------------------------|-------|
| Tape Width             | 12mm  |
| Reel Size              | 7inch |
| Device Cavity Pitch    | 8mm   |
| Devices Per Reel       | 1k    |

### Lead plating finish

100% Tin Matte finish

(All BeRex products undergoes a 1 hour, 150 degree C, Anneal bake to eliminate thin whisker growth concerns.)

### MSL / ESD Rating

**ESD Rating:** Class 1C  
**Value:** ±1000V  
**Test:** Human Body Model (HBM)  
**Standard:** JEDEC Standard JS-001-2017

**ESD Rating:** Class C3  
**Value:** ±1000V  
**Test:** Charged Device Model (CDM)  
**Standard:** JEDEC Standard JS-002-2018

**MSL Rating:** Level 1 at +260°C convection reflow  
**Standard:** JEDEC Standard J-STD-020



Proper ESD procedures should be followed when handling the device.

### RoHS Compliance

This part is compliant with Restrictions on the use of certain Hazardous Substances in Electrical and Electronic Equipment (RoHS) Directive 2011/65/EU as amended by Directive 2015/863/EU.

This product also is compliant with a concentration of the Substances of Very High Concern (SVHC) candidate list which are contained in a quantity of less than 0.1%(w/w) in each components of a product and/or its packaging placed on the European Community market by the BeRex and Suppliers.

### NATO CAGE code:

|   |   |   |   |   |
|---|---|---|---|---|
| 2 | N | 9 | 6 | F |
|---|---|---|---|---|